

Using Constraint Solvers as an oracle, with CPMpy

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Talk consists of

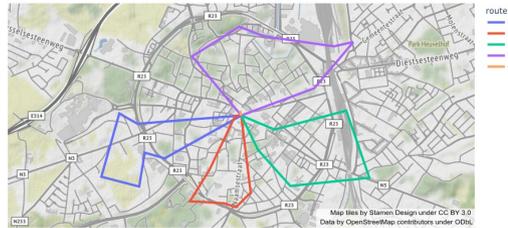
1. Using Constraint Solvers as an oracle, with CPMpy
2. Explaining (un)satisfiability: examples of master/sub-problem solving
3. Advanced examples: Explaining Optimality (using logic cutting-planes)

Conclusion, outlook and questions

Constraint solving

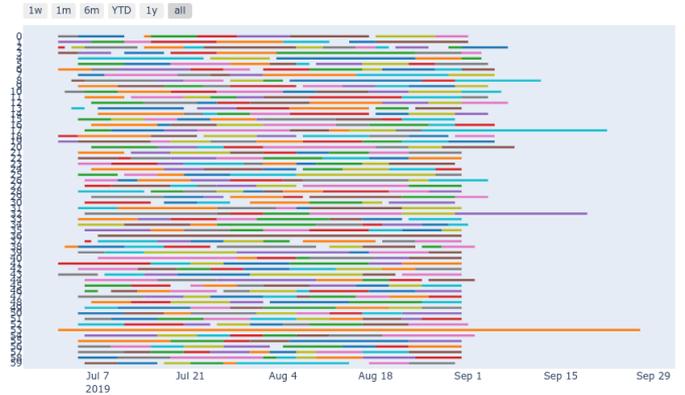
“Solving combinatorial optimisation problems”

- Vehicle Routing

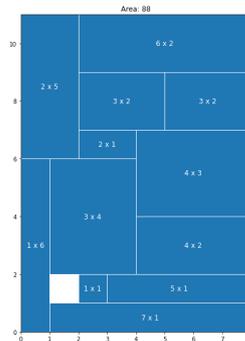


- Scheduling

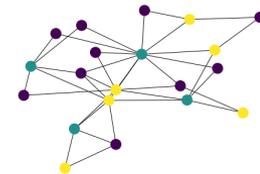
P-Large-02 (59 ROOMS), ExitStatus.OPTIMAL (1558.940814725 seconds)



- Packing



- Other combinatorial problems



Solving paradigm

Model



+

Solve

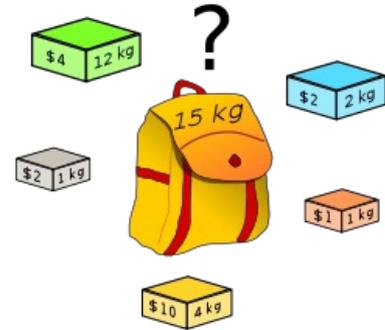


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Modeling

Knapsack:



Model =

- Variables, with a domain
- Constraints over variables
- Optionally: an objective

- $gr, bl, og, ye, gy :: \{0,1\}$

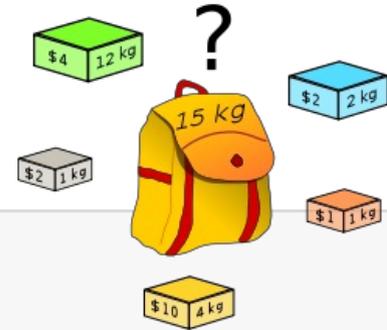
- $12*gr + 2*bl + 1*og + 4*ye + 1*gy \leq 15$

- $\text{maximize}(4*gr + 2*bl + 1*og + 10*ye + 2*gy)$

Model.solve()

Modeling

Knapsack:



Model =

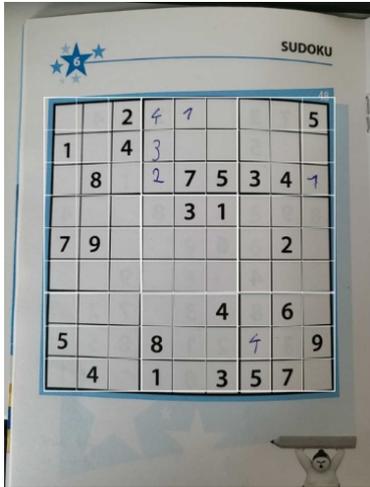
- Variables, with a domain
- Constraints over variables
- Optionally: an objective

Model.solve()

```
model = Model()
gr,bl,og,ye,gy = boolvar(shape=5)
model += (12*gr + 2*bl + 1*og + 4*ye + 1*gy <= 15)
model.maximize(4*gr + 2*bl + 1*og + 10*ye + 2*gy)
model.solve()
```

```
print(gr.value(), bl.value(), og.value(), ye.value(), gy.value())
```

```
0 1 1 1 1
```



Modeling

- Also satisfaction problems, e.g. *sudoku*

```
e = 0 # value for empty cells
given = np.array([
    [e, e, 2, 4, 1, e, e, e, 5],
    [1, e, 4, 3, e, e, e, e, e],
    [e, 8, e, 2, 7, 5, 3, 4, 1],

    [e, e, e, e, 3, 1, e, e, e],
    [7, 9, e, e, e, e, e, 2, e],
    [e, e, e, e, e, e, e, e, e],

    [e, e, e, e, e, 4, e, 6, e],
    [5, e, e, 8, e, e, 4, e, 9],
    [e, 4, e, 1, e, 3, 5, 7, e]])
```

```
model = Model()

# Variables
puzzle = intvar(1, 9, shape=given.shape, name="puzzle")

# Constraints on rows and columns
model += [AllDifferent(row) for row in puzzle]
model += [AllDifferent(col) for col in puzzle.T]

# Constraints on blocks
for i in range(0, 9, 3):
    for j in range(0, 9, 3):
        model += AllDifferent(puzzle[i:i+3, j:j+3])

# Constraints on values (cells that are not empty)
model += (puzzle[given!=e] == given[given!=e])

model.solve()
```

Other examples: room scheduling

Demo

https://github.com/CPMpy/cpmpy/blob/master/examples/room_assignment.ipynb



Example: room scheduling (backup slide)

```
def model_rooms(df, max_rooms, verbose=True):
    n_requests = len(df)

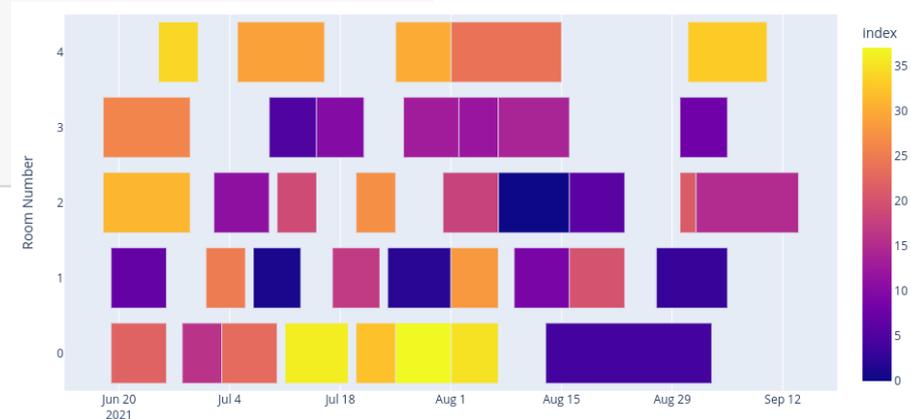
    # All requests must be assigned to one out of the rooms (same room during entire period).
    requestvars = intvar(0, max_rooms-1, shape=(n_requests,))

    m = Model()

    # Some requests already have a room pre-assigned
    for idx, row in df.iterrows():
        if not pd.isna(row['room']):
            m += (requestvars[idx] == int(row['room']))

    # A room can only serve one request at a time.
    # <=> requests on the same day must be in different rooms
    for day in pd.date_range(min(df['start']), max(df['end'])):
        overlapping = df[(df['start'] <= day) & (day < df['end'])]
        if len(overlapping) > 1:
            m += AllDifferent(requestvars[overlapping.index])

    return (m, requestvars)
```



Solving



- `model.solve()`
- Depends on solver family...
- SAT: *Boolean* decision variables; *clauses* as constraints
- MIP: *Integer* decision variables; *linear* constraints
- CP: *Integer* decision variables; *logical, mathematical, global* constraints

The changing role of solvers

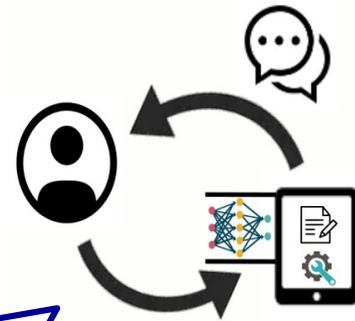
Holy Grail: user specifies, solver solves [Freuder, 1997]

I think we reached it... MiniZinc, Essence

- “Beyond NP” → Constraint Solver as an **oracle**
- Use CP solver to solve subproblem of larger algorithm
- Iteratively build-up and solve a problem until failure
- Integrate neural network predictions (structured output prediction)
- Generate proofs, explanations, or counterfactual examples, ...



CHAT-Opt: Conversational **H**uman-**A**ware **T**echnology for **O**ptimisation



Towards **co-creation** of constrained optimisation solutions

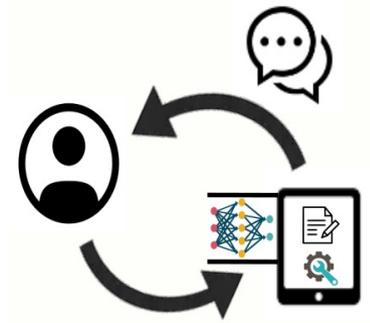
- Solver that learns from user and environment
- Towards conversational: explanations and stateful interaction

<https://people.cs.kuleuven.be/~tias.guns>

 @TiasGuns

Hiring post-docs!

Towards conversational solving

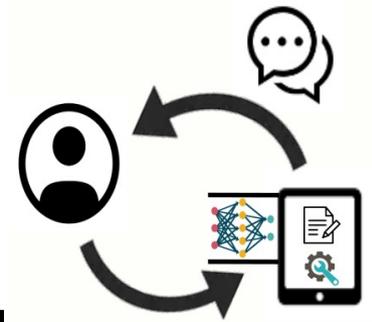


Asking for explanations

- Why is there no solution?
- How is this solution obtained?
- Why is X part of the solution?
- What are possible alternatives?
- What if Y should be part of the solution?

=> requires “Constraint Solving as oracle”

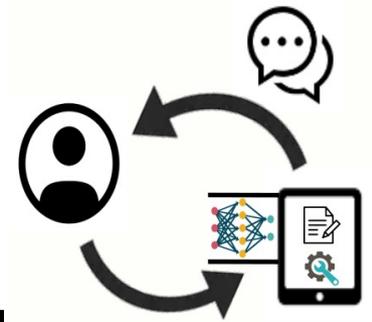
Conversational **H**uman-**A**ware Technology for **O**ptimisation



What would the ideal Constraint Solving system be?

- Efficient repeated solving
 - => Incremental
- Use CP/SAT/MIP or any combination
 - => solver independent and multi-solver
- Easy integration with Machine Learning libraries
 - => Python and numpy arrays

Conversational **H**uman-**A**ware Technology for **O**ptimisation



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Incrementality

- Solving:
 - MIP: can add constraints, change objective
(mechanisms not documented, e.g. start from previous basis)
 - SAT: *assumption* variables: can be toggled on/off when calling solve, adding constraints
(reuses learned clauses, variable activity)
 - CP: if CP-SAT, assumption variables like SAT, adding constraints and changing objective
 - SMT: all of the above and push/pop of constraints (Z3)
-
- Modeling?
 - Only if using solver API directly...
 - With CPMpy: part of the high-level modeling language!

Multiple solutions

```
x = intvar(0,3, shape=2)
m = Model(x[0] > x[1])

while m.solve():
    print(x.value())
    m += ~all(x == x.value()) # block solution
```

```
[3 0]
[3 1]
[3 2]
[2 0]
[1 0]
[2 1]
```

Returns True (sol. found) or
False (no solution)

Adds constraint
to model
(even if already
solved before)

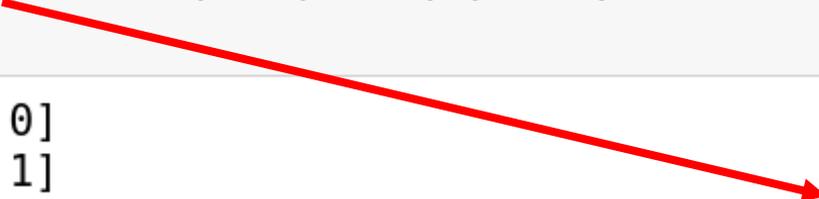
Alternative (diverse) solutions

```
# a diversity measure, hamming distance
def hamm(x, y):
    return sum(x != y)

x = intvar(0,3, shape=2)
m = Model(x[0] > x[1])

store = []
while m.solve():
    print(len(store), ":", x.value())
    m += ~all(x == x.value()) # block solution
    store.append(x.value())
    # maximize number of elements that are different
    m.maximize(sum(hamm(x, sol) for sol in store))
```

```
0 : [3 0]
1 : [2 1]
2 : [1 0]
3 : [3 2]
4 : [2 0]
5 : [3 1]
```



Can change
obj. function
(even if already
solved before)

Incremental room assignment problem

```
def model_rooms(df, max_rooms, verbose=True):
    n_requests = len(df)

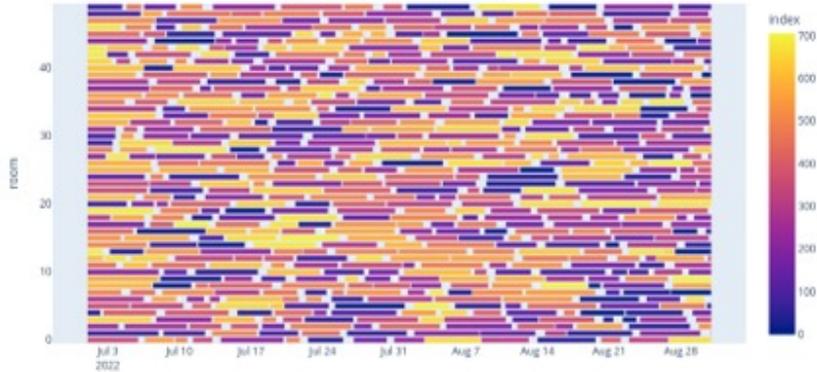
    # All requests must be assigned to one out of the rooms (same room during entire period).
    requestvars = intvar(0, max_rooms-1, shape=(n_requests,))

    m = Model()

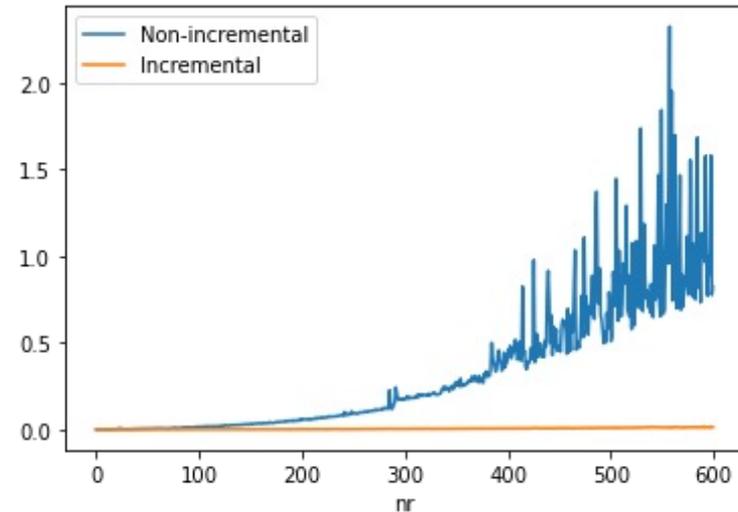
    # Some requests already have a room pre-assigned
    for idx, row in df.iterrows():
        if not pd.isna(row['room']):
            m += (requestvars[idx] == int(row['room']))

    # A room can only serve one request at a time.
    # <=> requests on the same day must be in different rooms
    for day in pd.date_range(min(df['start']), max(df['end'])):
        overlapping = df[(df['start'] <= day) & (day < df['end'])]
        if len(overlapping) > 1:
            m += AllDifferent(requestvars[overlapping.index])

    return (m, requestvars)
```



- Assume requests come in sequentially.
- Compute solution on every new request.



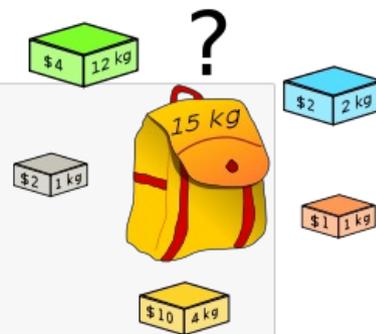
Multi-solver

- Same syntax, plus can reuse variables and their values

```
m_ort = SolverLookup.get("ortools", model_knapsack)
m_ort.solve()
print("\nOrtools:", m_ort.status(), ":", m_ort.objective_value(), items.value())

m_grb = SolverLookup.get("gurobi", model_knapsack)
m_grb.solve()
print("\nGurobi:", m_grb.status(), ":", m_grb.objective_value(), items.value())

# use ortools to verify the gurobi solution
m_ort += (items == items.value())
print("\tGurobi's is a valid solution according to ortools:", m_ort.solve())
```

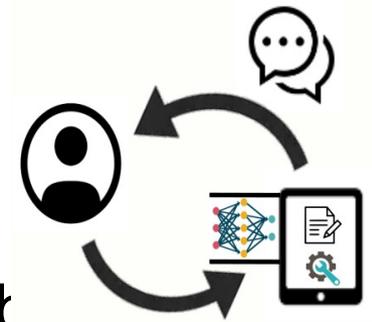


```
Ortools: ExitStatus.OPTIMAL (0.001146096 seconds) : 32.0 [ True False False True True True True True]
```

```
Gurobi: ExitStatus.OPTIMAL (0.0003108978271484375 seconds) : 32.0 [ True False True False True True True True]
```

```
    Gurobi's is a valid solution according to ortools: True
```

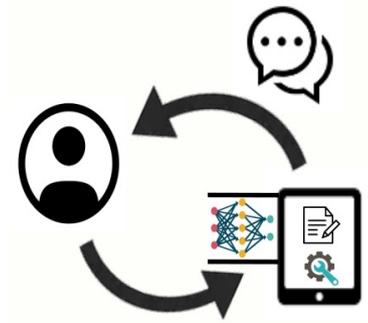
Conversational **H**uman-**A**ware Technology for **O**ptimisation



What would the ideal Constraint Solving system look like

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Conversational **H**uman-**A**ware **T**echnology for **O**ptimisation



- What would the ideal CP system be?

- Efficient repeated solving
 - => Incremental
- Use CP/SAT/MIP or any combination
 - => solver independent and multi-solver
- **Easy integration with Machine Learning libraries**
 - => **Python and numpy arrays**
 - Not covered, but see

https://github.com/CPMpy/cmpy/blob/master/examples/advanced/visual_sudoku.ipynb

3 short slides on CPMpy's design

- Design principle:
 - Aim to be a thin layer on top of solver API
 - Central concept: CPMpy expression

Design

CPMpy
(user code)

creates

Model

- constraints:
expression tree
 - objective:
expression tree
- expressions/*

- No rewriting!
- Like a parser



Hardest part

transformations/

Solver Interface

CPM_ortools

CPM_gurobi

CPM_minizinc

CPM_z3

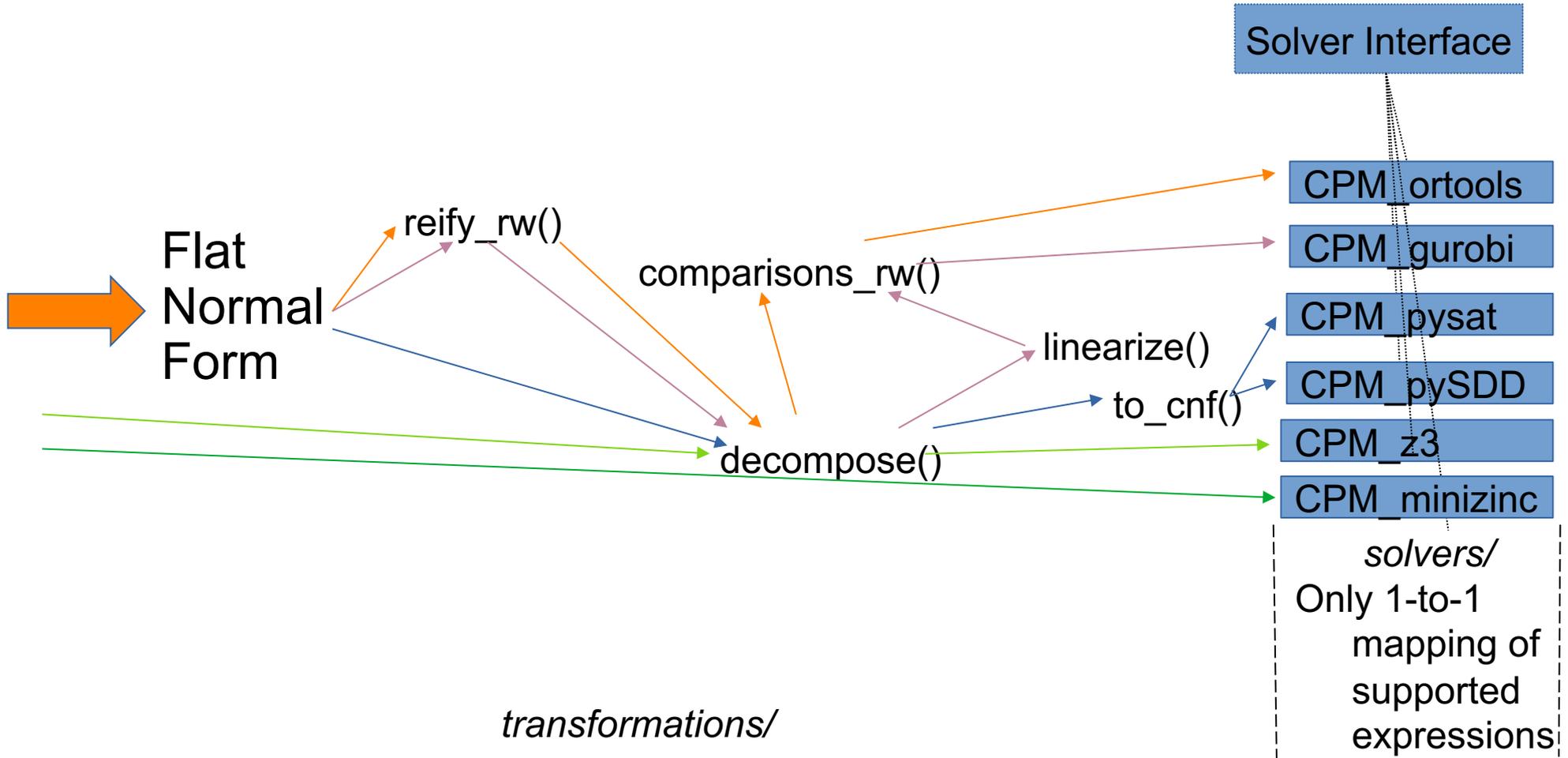
CPM_pysat

CPM_pySDD

solvers/

**Only 1-to-1
mapping of
supported
expressions**

Transformations in a nutshell



Solvers

Key principle: solver can implement any subset of expressions!

- Solvers can also choose to:
 - Support assumptions or not
 - Be incremental or not
 - Expose own solver parameters

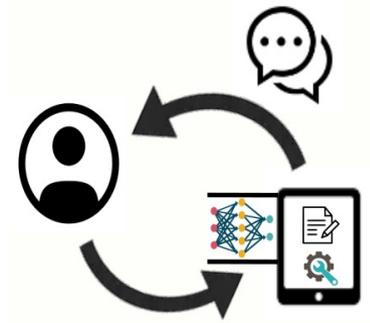
Currently:

- ortools
- pysat
- minizinc
- gurobi
- pySDD

Near future: ExactSolver, Z3

Wishlist: Mistral2, Geas, Gecode

Towards conversational solving



- Asking for explanations

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-

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