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Modelling of analyte profiles and band broadening generated by interface loops used in multi-dimensional liquid chromatography

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17 **Abstract**

18 Although two-dimensional liquid chromatography is gradually moving into mainstream use in
19 analytical laboratories, the lack of a complete theoretical foundation upon which sound
20 development decisions can be made impedes further advances. One aspect whose effect is
21 currently not fully understood is the shape and variance of the peak entering the second
22 dimension column when injected from an open loop interface. This is an important topic
23 because it is connected to several other variables encountered when developing 2D-LC
24 methods, including the first dimension flow rate, the sampling (modulation) time, and the loop
25 volume. In the present study, we have used both numerical simulation methods and
26 experimental measurements to understand and quantify the dispersion occurring in open
27 tubular interface loops. Variables included in the study are the analyte diffusion coefficient
28 (D_{mol}), loop filling and emptying rates (F_{fill} & F_{empty}), loop inner diameter or radius (R_{loop}) and
29 loop volume (V_{loop}). For a straight loop capillary we find that the concentration profile (as
30 measured at the loop outlet) depends only on a single dimensionless parameter $t_{empty}^* =$
31 $\frac{V_{loop}}{F_{empty}} \cdot \frac{D_{mol}}{R_{loop}^2}$ and the ratio of the filling and emptying flow rates F_{empty}/F_{fill} . A model depending
32 only on these two parameters was developed that allows prediction of the peak variance
33 resulting from the filling and emptying of a straight capillary operated in the first-in-last-out
34 (FILO) modulation mode. Comparison of the concentration profiles and the corresponding
35 variances obtained by either numerical simulation or experiments with straight capillaries
36 show that the results generally agree very well. When the straight capillary is replaced by a
37 tightly coiled loop, significantly smaller (20-40%) peak variances are observed compared to
38 those obtained with straight capillaries. The magnitude of these decreases is not predicted as
39 well by simulations, however the simulation results are still useful in this case, because they
40 represent an upper boundary (i.e., worst-case scenario) on the predicted variance.

41

42 **Keywords:**

43 Loop dispersion, numerical simulations, loop coiling, peak variance model, modulation, two-
44 dimensional liquid chromatography

45

46 **1. Introduction**

47 The use of analytical scale two-dimensional liquid chromatography (2D-LC) has increased
48 significantly in recent past years to address problems that can't be resolved by conventional
49 one-dimensional LC (1D-LC). It has not only been applied in the so-called "omics"-fields and
50 biopharmaceutical analysis, but also for small molecules analysis in the pharmaceutical and
51 chemical industry [1,2,3]. One of the main reasons for this evolution is the large increase in
52 commercially available instrumentation and software for 2D-LC. However, method
53 development still remains a bottleneck, in part due to insufficient fundamental understanding
54 of some key aspects of method development. The major challenges typically encountered
55 during method development include finding the optimal combination of separation
56 mechanisms in each dimension, and overcoming problems associated with the mismatch
57 between the properties of the mobile phases used in the two dimensions (e.g., peak splitting
58 due to large injections of "strong solvent" into the second dimension) [1,4].

59 The process by which fractions of first dimension (¹D) effluent are transferred to the second
60 dimension (²D) column is commonly referred to as "modulation" or "sampling" [5]. The
61 number and volume of fractions collected can also be important determinants of the quality
62 of a 2D-LC separation. For all modes of 2D-LC separation in use today (i.e., from simple single
63 heart-cut (LC-LC) to fully comprehensive (LC×LC)) [4], it is most common to transfer ¹D effluent
64 to the ²D column using a simple open tubular capillary. First, ¹D effluent flows from the ¹D
65 column outlet into the capillary for a time that determines the volume of each collected
66 fraction. Then – usually upon a valve switch – the capillary is connected to the ²D pump so
67 that its contents are displaced from the capillary and effectively "injected" into the ²D column.
68 The displacement step can be executed two different ways. When the fraction is displaced
69 from the capillary in the same flow direction in which it was collected, this is referred to as the
70 "First-In-First-Out" (FIFO) approach. When the fraction is displaced from the capillary in the
71 direction opposite from which it was collected, this is referred to as the "First-In-Last-Out"
72 approach. In the literature, different researchers tend to favor either FIFO or FILO, but we are
73 not aware of any thorough, systematic studies of the impact of these modulation approaches
74 (i.e., FIFO and FILO) on the performance of ²D separations. While it seems likely that the
75 impact of the modulation mode will be application dependent, we have shown in our own
76 work that the impact can be significant in at least some cases (e.g., see Fig. S4 in ref [6]).

77 The main focus of the present paper is dispersion that occurs in an open tubular loop during
78 modulation using the FILO mode. The FIFO case is sufficiently different that we will address it
79 in a different contribution.

80

81 **2. Experimental**

82 **2.1 Numerical Simulations**

83 **2.1.1. Simulation geometry and boundary conditions**

84 Fig. 1 illustrates the simulation geometry (aspect-ratio scaled with 1/1000) used in this work.
85 The species distribution computed in the actual simulation geometry (i.e., the upper half of
86 each plot) has been mirrored along the symmetry axis to provide a view of the full cross
87 section of the sample loop. By assuming we are working with a straight loop capillary, a 2D
88 axisymmetrical simulation geometry can be used to model the 3D cylindrical loop. This results
89 in a simplified geometry and requires less simulation time. For most conditions, the simulation
90 geometry was a 2D rectangle with a width (R_{loop}) of 175 μm and a length (L_{loop}) of 187.1 cm
91 resulting in a loop volume of 160 μL . Only for the conditions where peak volumes larger than
92 80 μL were explored, a larger geometry (360 μL) was used to avoid sample loss at the outlet
93 [7].

94 The top edge of the geometry was assigned as a wall with a no-slip boundary condition and a
95 zero normal concentration gradient (i.e., a zero flux wall condition). The bottom edge was
96 assigned as a symmetry axis with a zero normal concentration and velocity gradient. During
97 the filling of the loop, the left side of the geometry (width R_{loop}) is treated as a mass flow inlet
98 while the right side is treated as a pressure outlet with a zero-gauge pressure. To simulate
99 how the loop is emptied (i.e., when the flow is reversed for FILO operation), the boundary
100 conditions for the left and right sides are simply reversed. The different t_{empty}^* (for the
101 definition of t_{empty}^* see section 3.1) and F_{empty}/F_{fill} values considered in this study were the
102 result of different filling flow rates (F_{fill}), loop emptying flow rates (F_{empty}), diffusion coefficients
103 (D_{mol}), and filling volumes (i.e., $V_{fill} = F_{fill} \cdot t_{fill}$).

104

105 2.1.2 Simulation procedure and post processing

106 To simulate the filling process, a step function in mass fraction ($C_{in} = 0.01$) is set at the inlet of
 107 the capillary to fill the loop at a flow rate F_{fill} . The duration of the filling step was always chosen
 108 such that the total volume of sample entering the loop maximally occupied half the loop
 109 volume or less to avoid any analyte loss at the outlet [7]. In the emptying step (Fig. 1b-d), the
 110 flow direction is reversed (with a given F_{empty}/F_{fill} ratio), emptying the loaded sample plug out
 111 of the same end of the loop from which it was loaded. It is clear from Figs. 1c-d that sample
 112 molecules that diffused towards the low velocity region near the wall take a long time to
 113 empty from the sample loop. Temporal emptying concentration profiles $C_{out}(t)$ were obtained
 114 at the outlet during emptying (i.e., the inlet during sample filling becomes the outlet during
 115 emptying) by recording at each time step the flow rate averaged concentrations defined as:

$$116 \quad C_{out}(t) = \frac{\iint_S u_s \cdot c_s \cdot dS}{\iint_S u_s \cdot dS} \quad (1)$$

117 with u_s the local axial velocity across the outlet, c_s the local analyte concentration across the
 118 outlet, and S the surface area of the outlet. Normalized emptying profiles were subsequently
 119 created by plotting $C_{out}(t)/C_{in}$ as a function of the time t (e.g., see Fig. S1 of the Supplementary
 120 Material) or the normalized volumetric equivalent of the time ($F_{empty} \cdot t / V_{fill}$, see Fig. 3a).

121 From the emptying profile, the volumetric peak variance σ_v^2 was calculated using the moment
 122 expressions given in Eqs. (2), (3) and (4):

$$123 \quad MOM_i = \int_0^{t_f} C_{out}(t) \cdot t^i \cdot dt \quad (2)$$

$$124 \quad \sigma_t^2 = \frac{MOM_2}{MOM_0} - \left(\frac{MOM_1}{MOM_0} \right)^2 \quad (3)$$

$$125 \quad \sigma_V^2 = \sigma_t^2 \cdot F_{empty}^2 \quad (4)$$

126 With MOM_i the i^{th} order moment of the concentration profile of the analyte exiting the loop,
 127 σ_t^2 the time-based peak variance, F_{empty} the flow rate during displacement of the sample from
 128 the loop and t_f the time at which $C_{out}(t)/C_{in}$ drops to 0.001. The latter condition was chosen
 129 because this is also the cut-off used to integrate the experimental emptying profiles.

130 An important assumption made is that the mobile phase entering the loop during filling and
 131 emptying of the loop is the same and equal to the composition of the liquid present in the

132 loop before the start of filling (save the addition of the tracer analyte during filling). Given the
133 large number of possible combinations of mobile phase solvents, we have elected to focus on
134 this case. In practice, differences between the compositions of the solvent entering the loop
135 and solvent remaining in the loop from prior work may lead to effects other than those
136 observed in the present study, including, for example, dynamics effects as a result of
137 differences in viscosities (e.g. viscous fingering), incomplete mixing between the solvents, etc.

138 **2.1.3 Mesh**

139 A total of 1,496,700 cells of a rectangular structured grid were used to mesh the modeled 2D
140 geometry. The number of cells along the flow axis was 74,835, whereas 20 cells were used
141 along the radial axis. All cells had an axial length of 25 μm , while their radial length varied
142 between 1 μm near the wall and 30 μm near the symmetry axis with a 1.195 height growth
143 rate, to better capture the larger velocity differences between adjacent cells near the wall.

144 To perform a grid check, a mesh having four times more cells than the standard grid described
145 above was generated by halving the length and width of each cell. Subsequently, the values
146 of σ_v^2/V_{fill}^2 were calculated using the new grid for a low and a high value of t_{empty}^* (resp., $1 \cdot 10^{-5}$
147 and 0.8) in combination with the two extreme ratios of F_{empty}/F_{fill} (0.7 and 20). The obtained
148 values of σ_v^2/V_{fill}^2 were then compared to their corresponding values obtained by the
149 standard grid. The difference between values obtained using the two grids never exceeded
150 0.5%. The validity of the standard time step ($1 \cdot 10^{-4}$ s) was also checked by doing the same
151 comparison as for the grid check. It was found that the difference between the σ_v^2/V_{fill}^2 values
152 obtained with the standard time step and the ones obtained with a time step of $1 \cdot 10^{-5}$ s never
153 exceeded 0.3%.

154 **2.1.4 Solver settings**

155 The velocity and concentration fields were determined by solving the conservation equations
156 for mass and momentum and the convection-diffusion equation using the finite volumes
157 solvers of Ansys Fluent® with double precision. When solving the steady-state velocity fields,
158 the pressure-based coupled solver with second order upwind spatial momentum
159 discretization and second order spatial pressure discretization was used. When solving the
160 transient concentration fields, first order upwind spatial discretization and second order

161 implicit temporal discretization was used. Gradients were evaluated using the Least Squares
162 Cell Based method [7, 8].

163 **2.1.5 Software and hardware**

164 All simulations were performed with Ansys Fluent 19.2 software on Dell Power Edge R210
165 Rack Servers, with an Intel Xeon x3460 processor (clock speed 2,8 GHz, 4 cores) and 16 Gb,
166 1333 MHz ram memory running Windows server edition 2008 R2(64-bit) as an operating
167 system.

168 **2.2 Experimental elution profiles**

169 All reagents were used as obtained from their respective manufacturers. Methanol (MeOH,
170 HPLC Grade $\geq 99.9\%$), isopropanol (IPA, HPLC Grade $\geq 99.9\%$), and uracil were all obtained
171 from Sigma-Aldrich (St. Louis, MO). Water was purified in-house using a Milli-Q water
172 purification system (Billerica, MA).

173 The experimental setup used to determine the breakthrough profiles for the sample loop is
174 illustrated schematically in Fig. 2. Pumps 1 and 2 (G7120A) were binary pumps from Agilent
175 Technologies (Waldbronn, Germany). The 8-port/2-position switching valve (p/n: 5067-4214)
176 and variable wavelength (VWD) UV absorbance detector (G7114B; 2 μL flow cell G1314-
177 60187) were also from Agilent. The instrument was controlled using Agilent ChemStation
178 software (C.01.07 SR3 [465]), and raw absorbance data were exported from ChemStation to
179 .csv files for further treatment.

180 Emptying profiles were measured using the same 84.1 \pm 0.7 μL test capillary as described in
181 section 2.3 of the previous paper [7]. Emptying profiles were obtained twice for each condition
182 studied, once with the capillary stretched out straight, and once with the capillary coiled to a
183 diameter of 5.7 cm. The procedure was as follows. First, the loop capillary was flushed with at
184 least three volumes (i.e., about 240 μL) of mobile phase (e.g., 50/50 ACN/H₂O) using Pump 2
185 as shown in Fig. 2. Then, the valve was switched such that Pump 1 – which pumped the same
186 mobile phase as in Pump 2 but with 10 $\mu\text{g}/\text{mL}$ of uracil added – was connected to the loop
187 capillary, and filled for an amount of time corresponding to the desired fill volume of 30 μL .
188 Finally, the valve was again switched (the time of the programmed switch was treated as time
189 zero) such that Pump 2 was reconnected to the loop capillary, and data were collected for a

190 time corresponding to three loop volumes of liquid pumped through the capillary. This process
191 was repeated five times, each time resulting in profiles like those shown in Fig. 6b, Fig. S6 (B),
192 and Fig. S7 (B). A list of all experimental settings is given in the Supplementary Material in
193 Tables TS1, TS2 and TS3.

194

195 **3. Results and discussion**

196 **3.1 Simulated concentration profiles and broadening model**

197 Simulated concentration profiles for the outlet of the loop expressed in volumetric units
198 ($V_{empty}=F_{empty}\cdot t$) and normalized by the volume loaded into the sample loop (V_{fill}), are
199 presented in Fig. 3a for a filling flow rate (F_{fill}) of 0.25 mL/min, an emptying flow rate (F_{empty})
200 of 2 mL/min ($F_{empty}/F_{fill}=8$) and four different filling volumes. Non-normalized profiles are
201 shown in Fig. S1 of the Supplementary Material. It is important to note here that the step-like
202 variation in concentration observed at the start of emptying (note: to more clearly represent
203 this, the curve starts at -0.5 on the x-axis) is due to the fact that the emptying profile in this
204 numerical study is monitored directly at the outlet of the capillary in the simulation. This is
205 different from a physical experiment (using e.g. a 2D-LC setup or the one used in Fig. 2) where
206 the injected sample must first travel through a valve and additional connecting capillary before
207 reaching the detector.

208 A rather complex behavior is found for the different V_{fill} values, with the curves crossing
209 multiple times. It is noteworthy that the concentration plateau at the start of emptying step
210 increases with increasing fill volume. It is also interesting that the tailing part obtained for the
211 largest filling volume (red curve) is steeper and shorter than for the smaller volumes. Besides
212 the filling volume, the effects of other parameters including diffusion coefficient, loop
213 diameter and filling/emptying flow ratios were investigated. It was found that perfectly
214 overlapping dimensionless emptying profiles are obtained when two conditions are met. First,
215 the ratio of filling and emptying flow rates F_{empty}/F_{fill} should be the same. Second, the emptying
216 profiles should have the same dimensionless emptying time constant t_{empty}^* , defined as:

$$217 \quad t_{empty}^* = \frac{V_{fill} \cdot D_{mol}}{F_{empty} \cdot R_{loop}^2} \quad (5)$$

218 The physical interpretation of this time constant is that it represents the ratio of the time
219 needed to empty the volume equivalent of the fill volume (i.e. V_{fill}/F_{empty}) to the time needed
220 for diffusion across the radius of the loop (i.e., D_{mol}/R_{loop}^2). For example, when considering a
221 sample loop which is twice as wide, the same dimensionless emptying profile is found for a fill
222 volume that is four times larger, assuming all other parameters remain the same. The effect
223 of the ratio F_{empty}/F_{fill} on the dimensionless emptying profiles is illustrated in Fig. 3b. It is not
224 surprising that this parameter plays an important role in the shape of the emptying profiles as
225 it, in combination with t_{empty}^* , represents the relative time for radial diffusion during emptying
226 and filling (see also the definition of t_{fill}^* in Eq. (11)). These observations are consistent with
227 the results from Deridder et al. [8] who investigated the band broadening during sample
228 injection using a flow-through needle injection for 1D-LC and noted the emergence of the
229 same two dimensionless numbers. In fact, the geometry and assumptions underlying this
230 earlier study are the same as those presented here. The main physical difference with the flow
231 through-needle injection is that in that case there is usually a few seconds hold between
232 loading sample into the needle and emptying the needle due to the time needed for the
233 needle to move from the sample vial to the needle seat. In 2D-LC, especially in the
234 comprehensive mode of separation (LC×LC), this time is much shorter, and was assumed to
235 be negligible in the simulations described here. In other 2D-LC applications, such as multiple
236 heart cutting, this assumption is of course no longer valid. Since the dimensionless elution
237 profiles are the same when F_{empty}/F_{fill} and t_{empty}^* are constant, the resulting normalized peak
238 widths and peak variances (σ_V/V_{fill} or σ_V^2/V_{fill}^2) should also be the same if plotted vs. t_{empty}^*
239 for a given ratio of F_{empty}/F_{fill} . This is illustrated in Fig. 3c where we see that varying F_{empty}/F_{fill}
240 produces a curve that goes through a maximum. As previously explained in [8], low values of
241 t_{empty}^* correspond to conditions where the effects of the parabolic flow profile during filling
242 can be entirely compensated during emptying because the analyte molecules entering the
243 tube in the center do not have enough time to diffuse toward the wall before the flow is
244 reversed to empty the tube. At high t_{empty}^* the opposite occurs, i.e., there is enough time for
245 radial equilibration during filling and emptying and fewer analyte molecules will trail behind
246 by residing too long in the low velocity regions near the wall. The ratio of F_{empty}/F_{fill} in turn
247 reflects the relative time available for radial equilibration during both steps, affecting the
248 shape of the curve.

249 Two observations about the effect of F_{empty}/F_{fill} can be made, namely that the maximum value
 250 of σ_V^2/V_{fill}^2 increases with increasing F_{empty}/F_{fill} , and that the location of this maximum
 251 $(t_{empty}^*)_{max}$ shifts to higher t_{empty}^* values for lower F_{empty}/F_{fill} values. Several other F_{empty}/F_{fill}
 252 ratios were investigated to study these variations in more detail. It was found that the value
 253 of $(\sigma_V^2/V_{fill}^2)_{max}$ increases linearly with the square root of F_{empty}/F_{fill} in the range of
 254 investigated F_{empty}/F_{fill} values (0.7 to 40), as shown in Fig. 4a. The dependence of
 255 $(t_{empty}^*)_{max}$ on F_{empty}/F_{fill} was more difficult to model and finally we opted for a power law
 256 model with $(F_{fill}/F_{empty})^{0.7}$ (note the inverse ratio used) as shown in Fig. 4b. The resulting fitting
 257 functions are given below:

$$258 \quad \left(\frac{\sigma_V^2}{V_{fill}^2}\right)_{max} = 0.2 + 0.078 \cdot \left(\frac{F_{empty}}{F_{fill}}\right)^{0.5} \quad (6)$$

$$259 \quad (t_{empty}^*)_{max} = 0.06 \cdot \left(\frac{F_{fill}}{F_{empty}}\right)^{0.7} \quad (7)$$

260 We then investigated if the curves given in Fig. 3c and those for the other investigated
 261 F_{empty}/F_{fill} ratios would overlap if the σ_V^2/V_{fill}^2 and t_{empty}^* values would be normalized, i.e., by
 262 respectively dividing them by $(\sigma_V^2/V_{fill}^2)_{max}$ and $(t_{empty}^*)_{max}$, yielding the following
 263 parameters:

$$264 \quad Y = \frac{\sigma_V^2}{V_{fill}^2} / \left(\frac{\sigma_V^2}{V_{fill}^2}\right)_{max} \quad (8)$$

$$265 \quad X = \ln[t_{empty}^*/(t_{empty}^*)_{max}] \quad (9)$$

266 The results are presented in Fig. 5a, showing a good agreement for the different F_{empty}/F_{fill}
 267 curves in the range of values where we have both simulation and experimental results, i.e. -
 268 $1 < X < 3$ (the entire simulation range is shown in Fig. S2 in supplementary material). The x-axis
 269 was converted to the natural logarithm of $t_{empty}^*/(t_{empty}^*)_{max}$ to better present the range of
 270 low t_{empty}^* and because it results in a Gaussian-like shape for the data series, which is also
 271 centered around zero (since $\ln(1)=0$). Fitting all the curves for the different F_{empty}/F_{fill} values,
 272 the following fit function, which is overlaid in Fig. 5 (full black curve), is found:

$$273 \quad Y = 0.234 + 0.754 \cdot \exp\left(\frac{-X^2}{4.94}\right) \quad (10)$$

274 This single equation, in combination with the fit Eqs. (6) and (7), enables prediction of the peak
 275 variance for any possible combination of D_{mol} , R_{loop} , F_{fill} , F_{empty} , and V_{fill} for all possible F_{empty}/F_{fill}
 276 ratios between 0.7 and 40. To further explore the applicability of this fit, the simulations that
 277 were carried out with varying V_{fill} were repeated at a fixed value of V_{fill} , but with varying fill
 278 and empty flow rates and D_{mol} values, while maintaining a constant F_{empty}/F_{fill} value. These
 279 results, which are shown in Fig. 5b, again agree well with the fit function Eq. (a4) and confirm
 280 that this equation is universally valid as a good estimate for the σ_V^2 value of the concentration
 281 profile observed at the loop exit provided that the loop is a straight capillary and operated in
 282 the FILO mode. Such predictions can be obtained in the following manner:

- 283 1) values of Y can be calculated for $-1 < X < 3$ using Eq. (10);
- 284 2) $(\sigma_V^2/V_{fill}^2)_{max}$ and $(t_{empty}^*)_{max}$ can be determined using Eqs. (6) and (7) for a given
 285 value of F_{empty}/F_{fill} , which enables conversion of the X and Y values into a plot of σ_V^2/V_{fill}^2
 286 vs. t_{empty}^* ;
- 287 3) using the value of t_{empty}^* that can be calculated via Eq. (5) for a given set of conditions
 288 (D_{mol} , R_{loop} , F_{empty} , and V_{fill}) this plot can then be used to find the corresponding σ_V^2 value.

289 Whereas Fig. 5 compares the fit function with the simulation results in a normalized domain
 290 and a logarithmic scale (horizontal axis), Fig. S3 in supplementary materials shows that the
 291 agreement between the fit function and the simulated data is equally good in the physical
 292 σ_V^2/V_{fill}^2 vs. t_{empty}^* domain, similar to Fig. 3c.

293

294 As mentioned above, the ratio F_{empty}/F_{fill} in fact represents the ratio of the times available for
 295 analyte molecules to diffuse during the filling and emptying steps. This allows definition of a
 296 dimensionless fill time t_{fill}^* as:

$$297 \quad t_{fill}^* = \frac{V_{fill} \cdot D_{mol}}{F_{fill} \cdot R_{loop}^2} \quad (11)$$

298 Given that the V_{fill} , D_{mol} and R_{loop}^2 values to be used here are the same as those that apply
 299 during the emptying step, we can for the case of a straight capillary directly say that
 300 $t_{fill}^*/t_{empty}^* = F_{empty}/F_{fill}$. However, the D_{mol} factor is in fact representing the speed of species
 301 transport radially in the open tube, which, for purely laminar flow conditions, is only due to

302 diffusion as the radial velocity associated with convective transport is zero, by definition. Since
 303 sample loops of the dimensions studied here are usually coiled in practice, at high velocities
 304 the resulting centripetal forces can induce secondary radial flows that enhance radial mixing
 305 [7,9-16]. For cases where F_{empty} is larger than F_{fill} , which is almost always the case in 2D-LC, it
 306 is possible that this enhanced radial dispersion is more pronounced during emptying or even
 307 only present during emptying and not during filling. In that case, the factor F_{empty}/F_{fill} should
 308 be replaced by t_{fill}^*/t_{empty}^* , where for each t^* the value of D_{mol} should be replaced by the
 309 actual radial dispersion coefficient D_{rad} , yielding

$$310 \quad \frac{t_{fill}^*}{t_{empty}^*} = \frac{F_{empty} \cdot D_{rad,fill}}{F_{fill} \cdot D_{rad,empty}} \quad (12)$$

311 It was therefore of interest to know how this affected the obtained fitting function. Fig. S4
 312 shows a series data points obtained from simulations where V_{fill} was fixed and F_{empty}/F_{fill} was
 313 held constant, but instead of using a fixed D_{mol} value (which will yield the results of Fig. 5b),
 314 D_{rad} was applied for the emptying step ($D_{rad,empty}$) and filling ($D_{rad,fill}$). The values of D_{rad} were in
 315 fact the value of D_{mol} multiplied by a factor that represents the relative increase in radial
 316 transport that depends on the relevant flow rate (i.e., F_{empty} or F_{fill}). To estimate the
 317 approximate values of D_{rad} vs. flow rate, data obtained in an earlier study were used (see Fig.
 318 8 in [7]). When comparing the results of these simulations with the fit function when using
 319 F_{empty}/F_{fill} , a clear deviation is seen in any case where the flow rate is high enough to result in
 320 a $D_{rad} > D_{mol}$. Figure S5 in the supplementary material however shows that if t_{fill}^*/t_{empty}^* is
 321 used instead of F_{empty}/F_{fill} with the set $D_{rad,empty}$ and $D_{rad,fill}$ instead of D_{mol} , the fit still accurately
 322 predicts σ_V^2/V_{fill}^2 as for the cases with a constant D_{mol} . This again shows the strength of the
 323 obtained fitting function as it also enables prediction of the variance of the concentration
 324 profile at the loop exit even in cases where radial dispersion plays a role. It is of course
 325 required to have reliable data for the dependence of D_{rad} on F . As will be shown in the
 326 experimental results section, the dispersion predicted by simulations using D_{mol} in fact
 327 represents a limiting worst-case scenario.

328 **3.2 Comparison of simulated and experimental elution**

329 To verify the simulated emptying profiles and the dispersion model given by Eqs. (6)-(10), a
 330 series of experimental emptying profiles were measured using a straight loop, as described in

331 Section 2.2. In Fig. 6, simulated emptying profiles (6A) are compared with experimental ones,
332 both obtained at $F_{empty}/F_{fill} = 8$ for different values of t_{empty}^* . The resemblance of the trailing
333 ends of the peaks is striking, even showing very similar behavior in the crossing over of the
334 profiles over the course of the time axis. As previously mentioned, the front of the
335 experimental profile is more rounded than the step-like shape obtained from the simulations
336 due to the dispersion occurring between the outlet of the loop capillary and the UV-detector,
337 which is not included in the simulations. Similarly good agreement between the experimental
338 and simulated profiles was obtained for $F_{empty}/F_{fill} = 1$ and $F_{empty}/F_{fill} = 20$, as shown in Figs. S6
339 and S7 in the Supplementary Material. To obtain the appropriate range of t_{empty}^* values for
340 the latter case, a more viscous mobile phase was used (isopropanol/water 50/50 v%/v% vs.
341 methanol/water 50/50 v%/v% used for $F_{empty}/F_{fill} = 1$ and 8). Under these conditions, the value
342 D_{mol} is reduced by a factor of two [7]. Note that there are small differences in t_{empty}^* due to
343 the difference between simulated and experimentally determined loop radii, and the
344 discretization of the valve switching time (i.e., minimum increment of 0.01 min) that did not
345 allow to exactly obtain the intended $V_{fill} = 30\mu\text{L}$ (see also Tables TS1, TS2 and TS3 in the
346 Supplementary Material).

347 Using the same method as for the simulated emptying profiles (see Experimental Section (Eqs.
348 (1)-(4)), the peak variance of these profiles was determined and, using Eqs. (6)-(9), converted
349 in the same dimensionless representation used in Fig. 5. For the $F_{empty}/F_{fill} = 1$, an excellent
350 agreement is found between the fitting function and the experimental results, as shown in
351 Fig. 7. For the two other ratios, an equally good agreement with the fit is found in the range
352 $0 < X < 3$. For values of $X < 0$, a deviation of the experimental results from the fit function is
353 observed, increasing to around 20% at $X = -1$. The precision of the results in this range is
354 however also poorer as indicated by the increasingly larger error bars ($\pm 1\sigma$) for lower X values.
355 To obtain these very low X values, very high emptying flow rates are used, making these
356 experiments more sensitive to multiple experimental factors including integration errors
357 (narrow peaks) and small variations in the valve switching time (on the order of milliseconds).
358 Nevertheless, the results show that, within acceptable accuracy, the variance of the
359 concentration profile observed at the exit of straight sample loops used in the FILO mode, for
360 a wide range of F_{empty}/F_{fill} and t_{empty}^* conditions, can be predicted.

361 As previously mentioned, the sample loops used in 2D-LC are typically coiled in practice, at
362 least with one half of a turn to make connection to the different valve ports on the modulation
363 valve, but often in multiple turns/coils. As a result, secondary flow effects will occur as the
364 result of centripetal forces, increasing the radial mixing of the analyte with the surrounding
365 solvent, making the system behave as if the analyte has a higher diffusion coefficient. These
366 effects become more pronounced at higher flow rate and as a result the datapoints in the low
367 t_{empty}^* range will be more affected. In addition, whereas for high F_{empty}/F_{fill} ratios, i.e., for low
368 F_{fill} flow rates, this effect only occurs during emptying, for low F_{empty}/F_{fill} ratios (~ 1) these
369 effects occur to the same extent during both filling and emptying. Figure 8 shows the
370 experimental results in a way similar to Fig. 7, and using the same loop, but now with the loop
371 coiled (dimensions coil given in the Experimental section) for different F_{empty}/F_{fill} ratios.
372 Whereas for high X values (low velocities) the data agree well with the fitting function,
373 especially for $F_{empty}/F_{fill}=1$, the values increasingly deviate from the fit as X decreases (i.e., for
374 high F_{empty} flow rates). If reliable and accurate data would be available describing the
375 enhancement of the radial dispersion as a function of flow rate, one could try to include these
376 in the theoretical model given by Eqs. (6)-(10), using the t_{fill}^*/t_{empty}^* ratio rather the F_{empty}/F_{fill}
377 ratio. Since this affects both the values of t_{empty}^* and t_{fill}^*/t_{empty}^* (the latter in both numerator
378 and denominator), independent measurements of D_{rad} are thus required to enable this
379 correction.

380 These results however show that the predictive model obtained and validated for dispersion
381 in the FILO mode in the straight loop provides a “worst-case scenario”-value for the band
382 broadening. For coiled loops, the enhanced radial mixing reduces this band broadening but
383 only to a rather limited extent (max. 40% around the maximum for $F_{empty}/F_{fill}=8$ and 20). The
384 fact that the smallest reduction is found for $F_{empty}/F_{fill}=1$ indicates that the advantages of the
385 enhanced radial transport occurring during the emptying step is countered by that fact that
386 during the filling step this enhanced radial transport tends to increase the amount of solutes
387 that are transported towards the low velocity region near the wall. As for the higher F_{empty}/F_{fill}
388 ratio the flow rate during emptying is always larger than during filling, the enhancement of
389 the radial transport is also always larger than during the filling stage.

390

391 4. Conclusions

392 We draw the following principal conclusions from this study.

- 393 1. The concentration profiles when emptying straight loops that were filled in the FILO
394 mode without sample loss at the outlet (i.e. 50% or less filling fraction) only depend on
395 the dimensionless elution time $t_{empty}^* = V_{fill} \cdot D_{mol} / (F_{empty} \cdot R_{loop}^2)$ and the ratio of
396 the filling and emptying flow rates F_{empty}/F_{fill} . The shape and relative position of the
397 simulated and experimental elution profiles correspond very well over the entire range
398 of investigated experimental conditions ($F_{empty}/F_{fill} = 1-20$).
- 399 2. The dependencies of normalized peak variances on t_{empty}^* depend on F_{empty}/F_{fill} and go
400 through a maximum. By normalizing these curves for the location and amplitude of
401 this maximum, a universal fit function was developed that allows prediction of the
402 variance of the peaks exiting from straight sample loops over a wide range of t_{empty}^* -
403 values that correspond to most conditions encountered in practice.
- 404 3. The universal fit function can also be applied in cases where centripetal forces cause
405 secondary flow effects in coiled loops, however this requires the use of the
406 t_{fill}^*/t_{empty}^* -ratio rather than the F_{empty}/F_{fill} -ratio.
- 407 4. Peak variances are significantly smaller when coiled loops are used compared to
408 straight loops. The straight loop case thus represents the worst-case scenario of the
409 band broadening that can be expected during the filling and emptying of the loop. If
410 very accurate data of the enhanced radial mixing due to centripetal forces as a function
411 of flow rate would be available, one could apply these to the model to improve the
412 prediction for coiled loops.

413 The trends discussed here should be of great use to practitioners of 2D-LC who are interested
414 in making estimates of the variance of the peaks injected into the second dimension column
415 during method development and optimization. The fact that these variances are exclusively
416 determined by t_{empty}^* and F_{empty}/F_{fill} should allow a relatively straightforward comparison of
417 this injection variance with the expected variance due to dispersion in the second dimension
418 column itself. In addition, this knowledge may influence decision making with respect to the
419 use of active modulation approaches (e.g., Active Solvent Modulation) that can be used to
420 mitigate dispersion of second dimension peaks that can result from unfavorable combinations
421 of solvent composition and volume of fractions injected into the second dimension (i.e.,
422 mobile phase mismatch).

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425 Foundation Flanders (FWO Vlaanderen). The work of T.L. and D.S. on this study has been
426 supported by a grant from the U.S. National Science Foundation (CHE-2003734). All of the
427 instrumentation used to obtain the experimental results was provided by Agilent
428 Technologies.

429 Figure Captions

430 Figure 1:

431 Illustration of concentration profiles during filling and emptying of a sample loop ($V_{fill} = F_{fill} \cdot t$
432 and $V_{empty} = F_{empty} \cdot t$). $F_{fill} = 0.25$ mL/min, $F_{empty} = 2$ mL/min, $D_{mol} = 1 \cdot 10^{-9}$ m²/s, $V_{loop} = 160$ μ L,
433 $L_{loop} = 187.1$ cm, $R_{loop} = 175$ μ L. (a) Filling time = 19.2 s, $V_{fill} = 80$ μ L. (b) Emptying time = 0.3 s,
434 $V_{empty} = 10$ μ L. (c) Emptying time = 0.9 s, $V_{empty} = 30$ μ L. (d) Emptying time = 1.8 s, $V_{empty} = 60$
435 μ L. Aspect ratio was adjusted for clarity by scaling L_{loop} with a factor of 1/1000.

436

437

438 Figure 2:

439 Schematic representation of experimental setup used to determine the breakthrough profiles
440 for (A) the capillary coiled and (B) with the capillary stretched out straight. Left panels
441 represent the filling step and right panels the emptying step.

442

443

444 Figure 3:

445 Simulated normalized emptying profiles as a function of the normalized emptying volume
446 ($F_{empty} \cdot t / V_{fill}$) (A) for different sample volumes ($V_{fill} = 10$ μ L (blue), 40 μ L (green), 80 μ L
447 (purple), 120 μ L (orange), 160 μ L (red)), with $F_{fill} = 0.25$ mL/min, $F_{empty} = 2$ mL/min, F_{empty}/F_{fill}
448 = 8 and $D_{mol} = 1 \cdot 10^{-9}$ m²/s. (B) Same data for $V_{fill} = 80$ μ L and $F_{fill} = 0.25$ mL/min, but with
449 different F_{empty}/F_{fill} ratios: $F_{empty}/F_{fill} = 1$ (dashed blue line), $F_{empty}/F_{fill} = 8$ (solid green line),
450 $F_{empty}/F_{fill} = 20$ (dotted red line). (C) Simulated normalized peak variance as a function of
451 dimensionless emptying time for different F_{empty}/F_{fill} ratios: $F_{empty}/F_{fill} = 1$ (blue circles),
452 $F_{empty}/F_{fill} = 8$ (green triangles) and $F_{empty}/F_{fill} = 20$ (red squares).

453

454

455 Figure 4:

456 (A) Plot of the maximum of the simulated normalized peak variance curves as a function of
457 $(F_{empty}/F_{fill})^{0.5}$. (B) Plot of the location of the maximum of the simulated normalized peak variance
458 curves as a function of F_{fill}/F_{empty} . The simulated F_{empty}/F_{fill} ratios are 0.7, 1, 2, 7, 8, 20, 40. The black
459 curves represents the fit equation.

460

461

462 Figure 5:

463 Fully normalized peak variance fit curve (black solid curve representing the fit Eq. (10)) and
464 the simulated data points obtained (A) using different loop filling volumes for different
465 F_{empty}/F_{fill} ratios: $F_{empty}/F_{fill} = 0.7$ (purple diamonds), 1 (blue circles), 2 (orange crosses), 7 (pink
466 hyphens), 8 (green triangles), 20 (red squares), 40 (black pluses). (B) Simulated data obtained
467 using a fixed loop filling volume ($V_{fill} = 30$ μ L) Blue circles: $F_{empty}/F_{fill} = 1$ and $D_{mol} = 5.56 \cdot 10^{-10}$
468 m²/s, green triangles: $F_{empty}/F_{fill} = 8$ and $D_{mol} = 5.56 \cdot 10^{-10}$ m²/s, red squares: $F_{empty}/F_{fill} = 20$ and
469 $D_{mol} = 2.74 \cdot 10^{-10}$ m²/s.

470

471 Figure 6:
472 Normalized emptying profiles as a function of emptying volume (A) simulated and (B)
473 experimental. For both $F_{empty}/F_{fill} = 8$ and $D_{mol} = 5.56 \cdot 10^{-10} \text{ m}^2/\text{s}$. Green dotted curves: $F_{fill} = 0.04$
474 mL/min, $F_{empty} = 0.32 \text{ mL/min}$, $t_{empty,sim}^* = 0.102$, $t_{empty,exp}^* = 0.091$. Blue dashed curves: $F_{fill} =$
475 0.23 mL/min , $F_{empty} = 1.84 \text{ mL/min}$, $t_{empty,sim}^* = 0.018$, $t_{empty,exp}^* = 0.016$. Red solid curves: $F_{fill} =$
476 0.55 mL/min , $F_{empty} = 4.4 \text{ mL/min}$, $t_{empty,sim}^* = 0.007$, $t_{empty,exp}^* = 0.006$.

477
478

479 Figure 7:
480 Fully normalized peak variance fit curve (black solid curve representing the fit Eq. (10)) in
481 addition to the experimental data points obtained using straight loops and with a fixed loop
482 filling volume of $V_{fill} = 30 \text{ } \mu\text{L}$. $F_{empty}/F_{fill} = 1$ and $D_{mol} = 5.56 \cdot 10^{-10} \text{ m}^2/\text{s}$ (blue circles), $F_{empty}/F_{fill} = 8$
483 and $D_{mol} = 5.56 \cdot 10^{-10} \text{ m}^2/\text{s}$ (green triangles), $F_{empty}/F_{fill} = 20$ and $D_{mol} = 2.74 \cdot 10^{-10} \text{ m}^2/\text{s}$ (red
484 squares).

485
486

487 Figure 8:
488 Fully normalized peak variance fit curve (black solid curve representing the fit Eq. (10)) in
489 addition to the experimental data points obtained using coiled loops and with a fixed loop
490 filling volume of $V_{fill} = 30 \text{ } \mu\text{L}$. $F_{empty}/F_{fill} = 1$ and $D_{mol} = 5.56 \cdot 10^{-10} \text{ m}^2/\text{s}$ (blue circles), $F_{empty}/F_{fill} = 8$
491 and $D_{mol} = 5.56 \cdot 10^{-10} \text{ m}^2/\text{s}$ (green triangles), $F_{empty}/F_{fill} = 20$ and $D_{mol} = 2.74 \cdot 10^{-10} \text{ m}^2/\text{s}$ (red
492 squares).

493

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Highlights:

- Filling and emptying of the fraction collection loops in first-in-last-out mode studied.
- Shape and variance of the peaks entering a second dimension column are investigated.
- Results only depend on dimensionless elution time and ratio of filling and emptying flow rates.
- Numerical model for peak variance of emptying peak profiles was numerically and experimentally verified.
- Tightly coiled loops exhibit narrower and less tailing peaks than straight capillaries.

Figure 1:

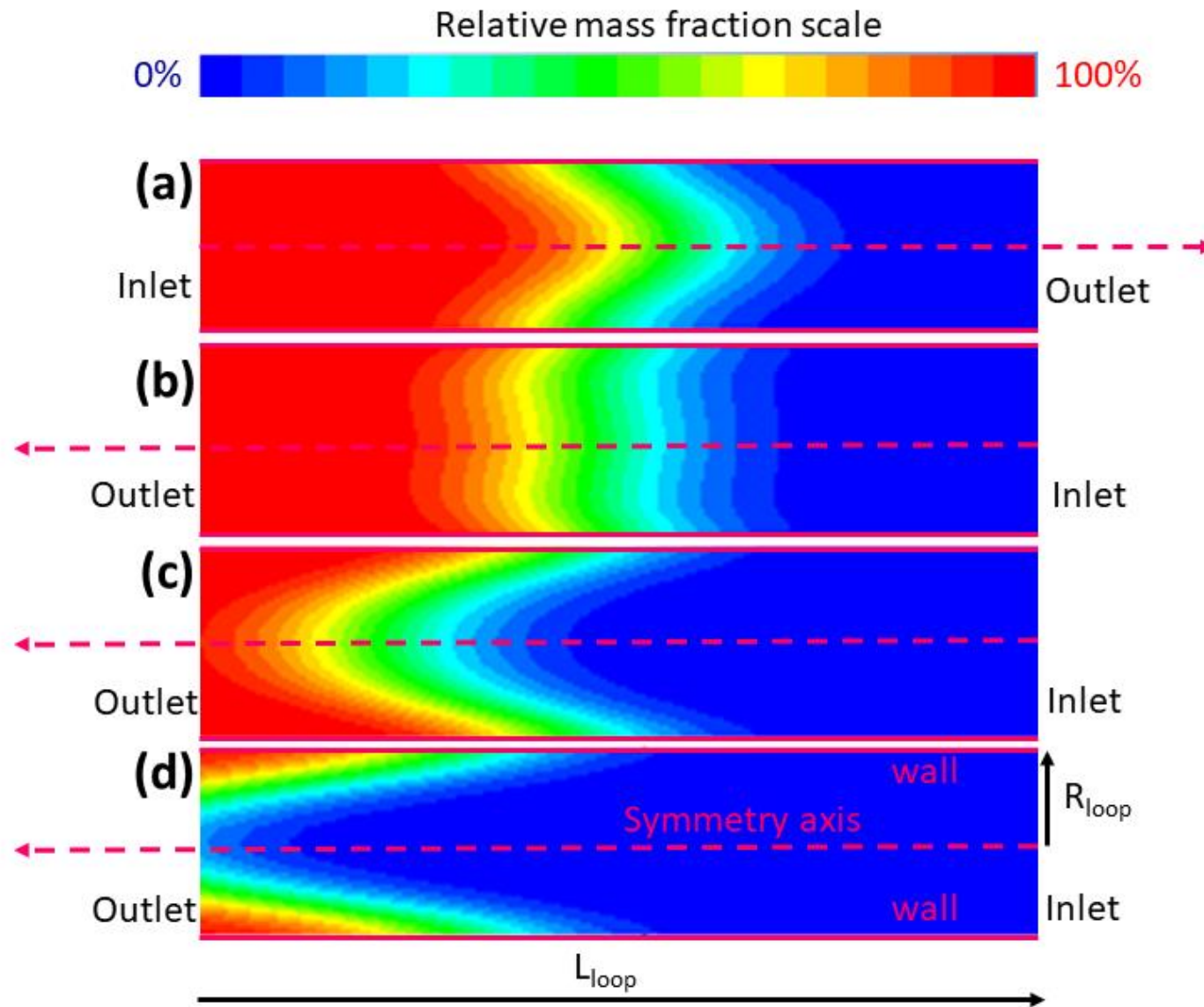
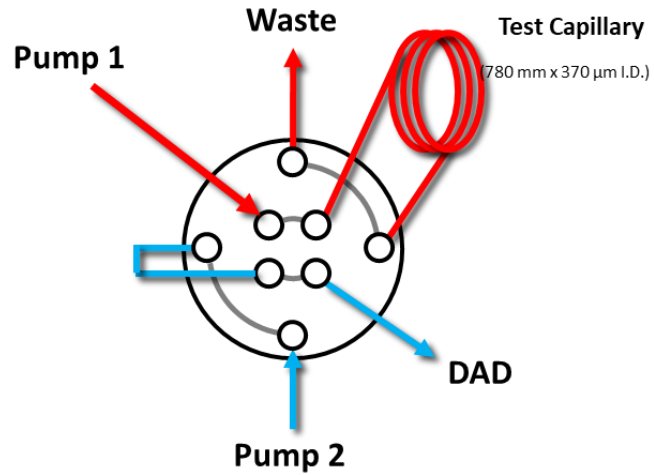
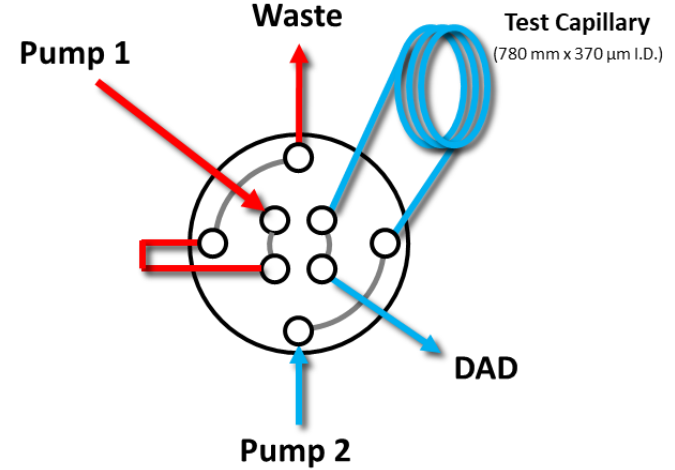


Figure 2:

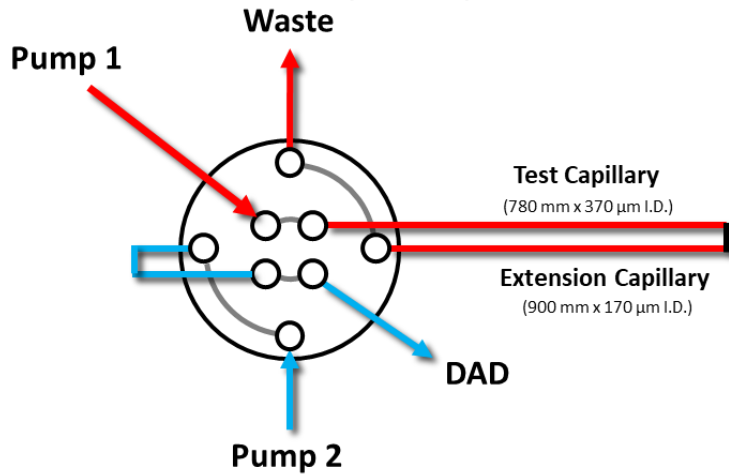
A Valve Position 1 ("Fill")



Valve Position 2 ("Empty")



B Valve Position 1 ("Fill")



Valve Position 2 ("Empty")

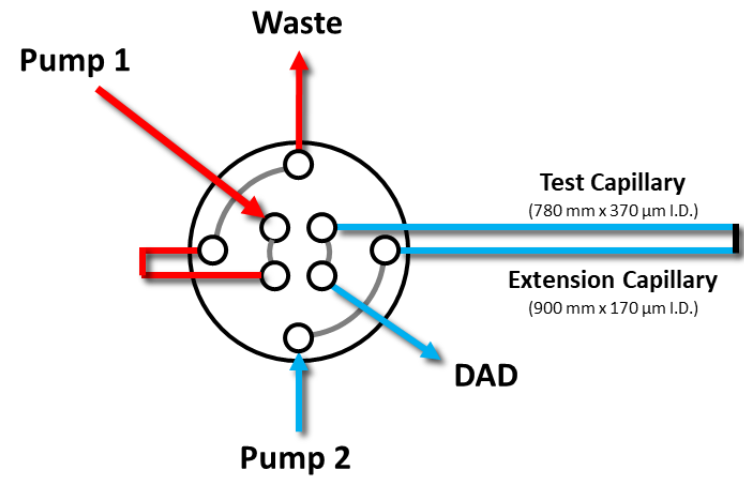
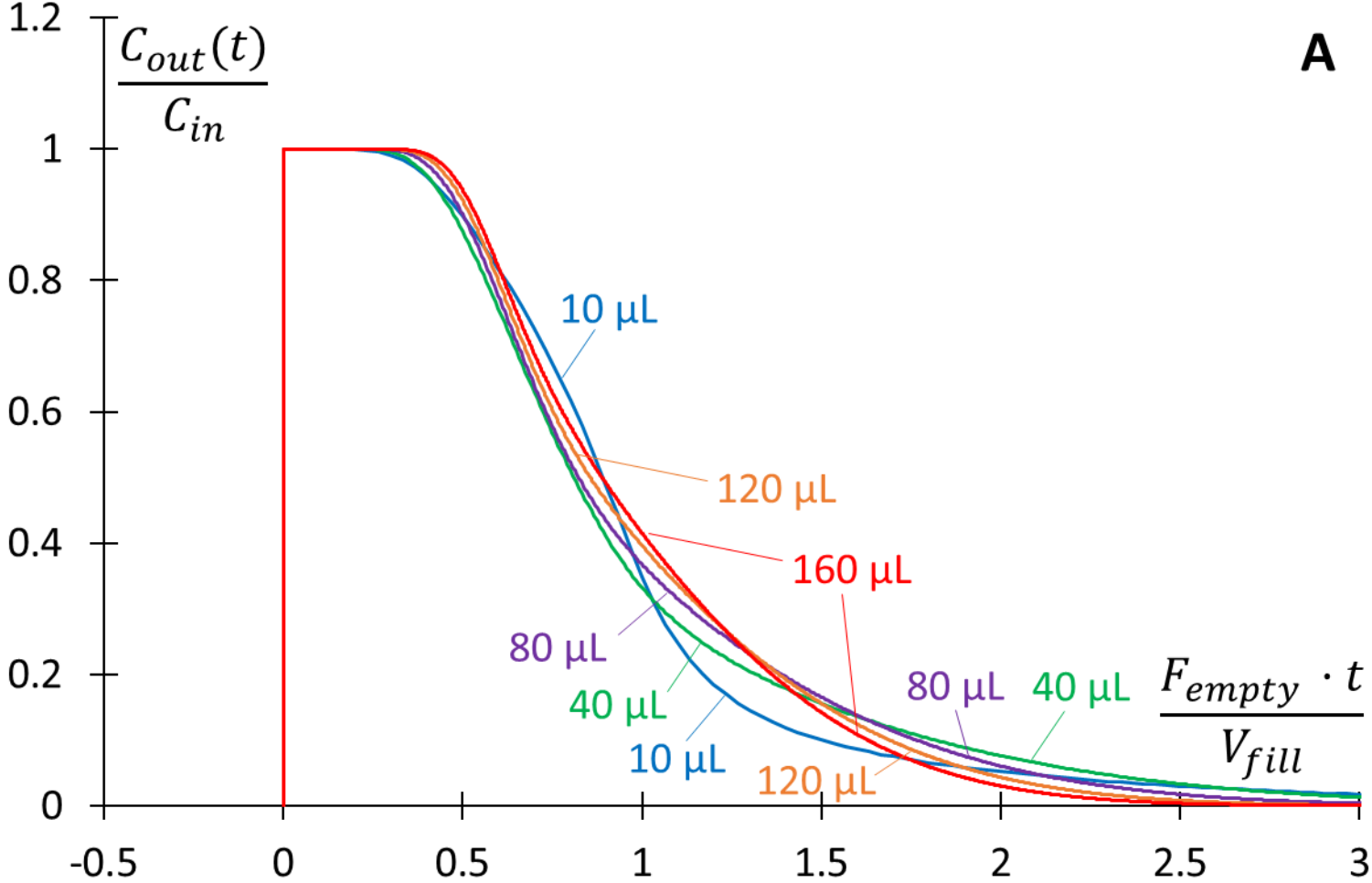
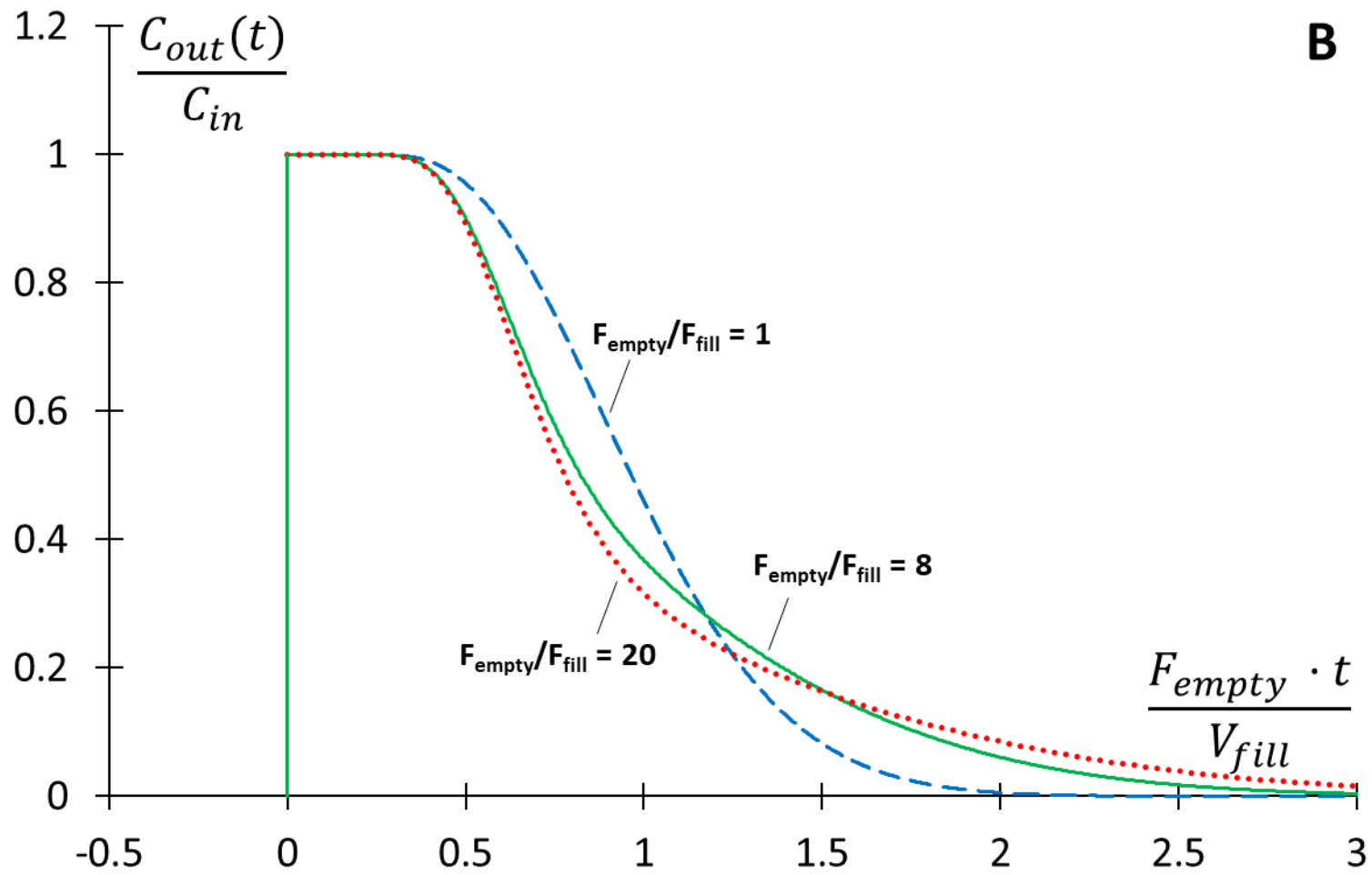


Figure 3:



A

B



C

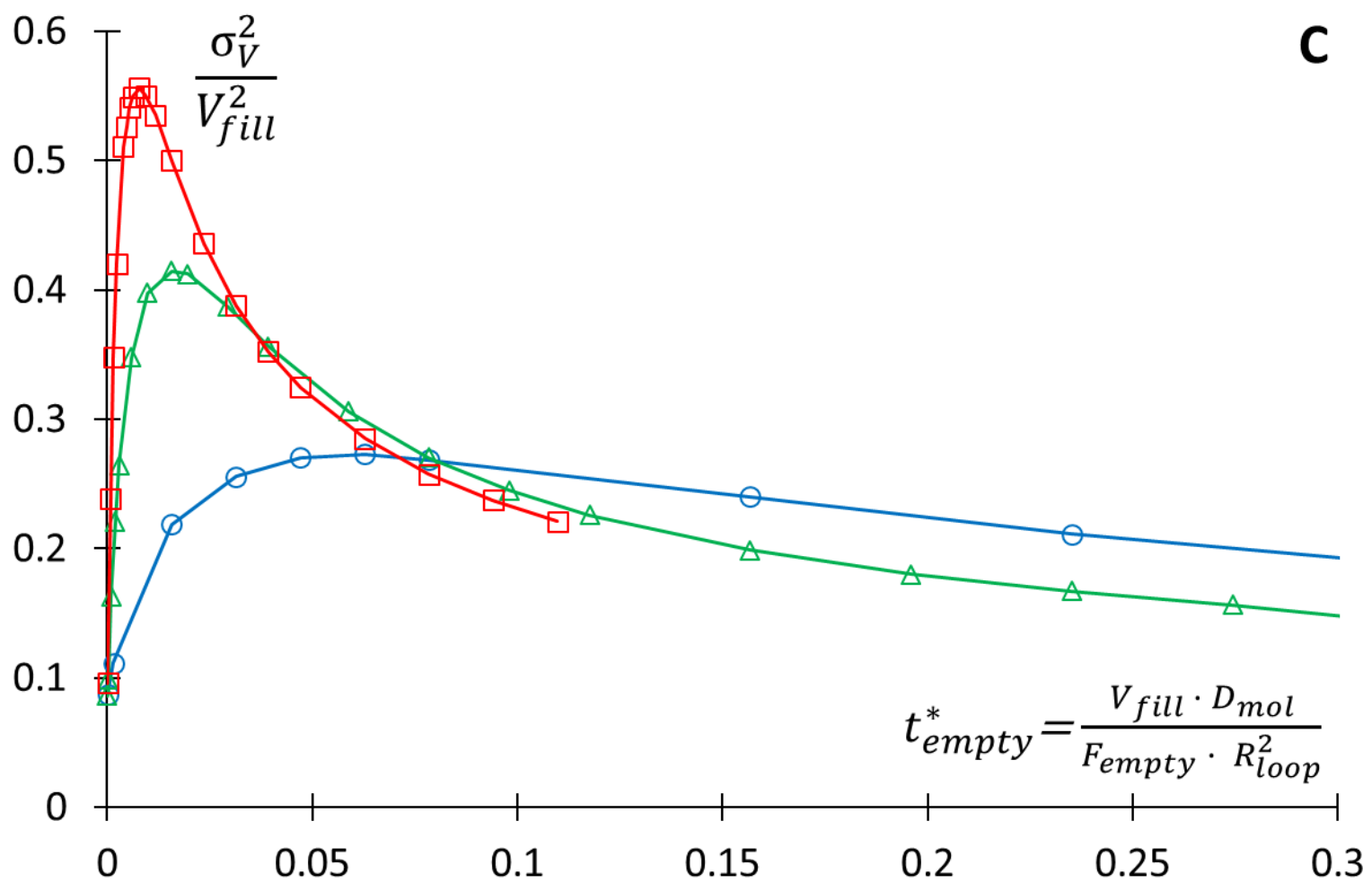
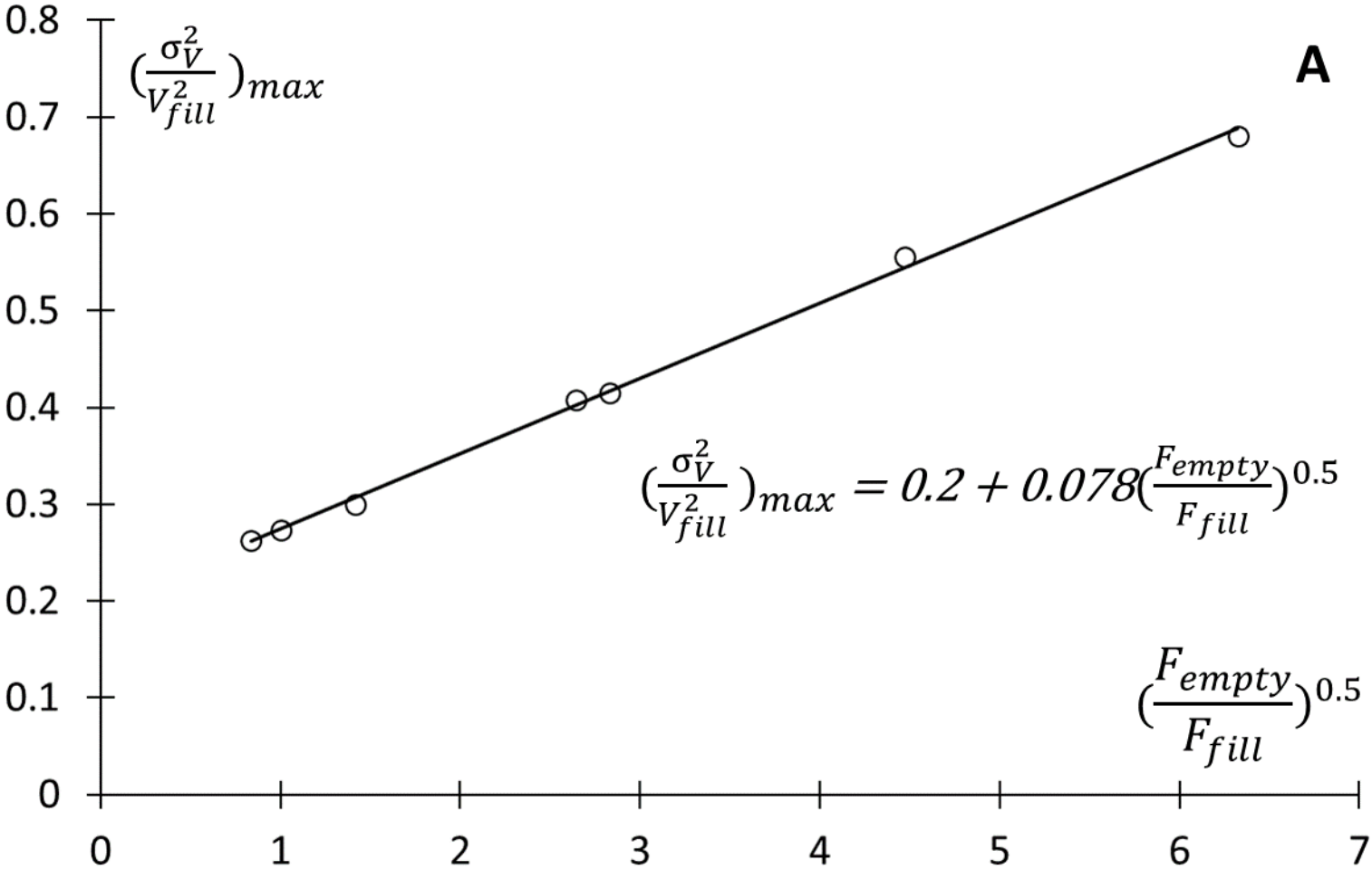


Figure 4:



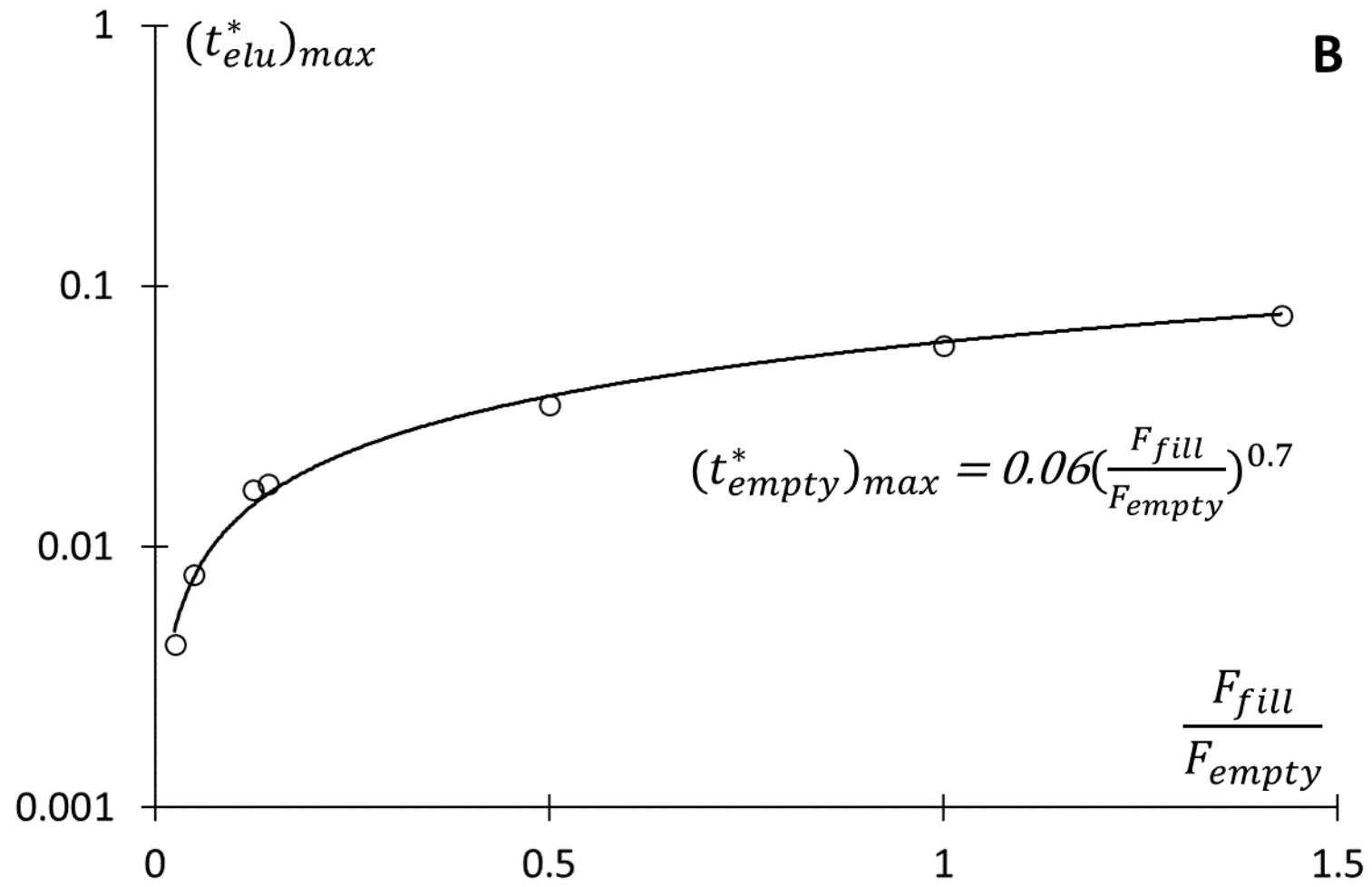
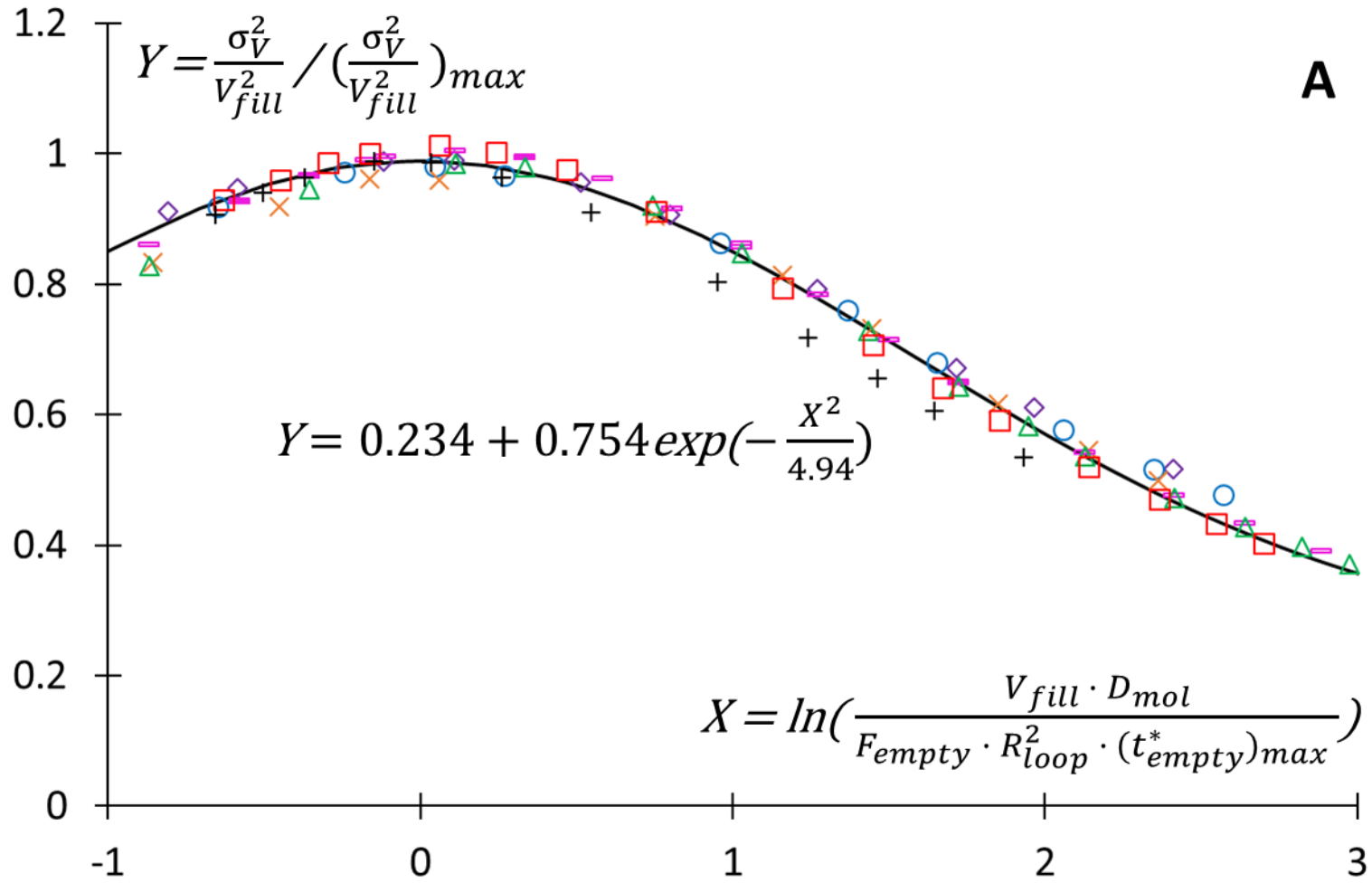


Figure 5:



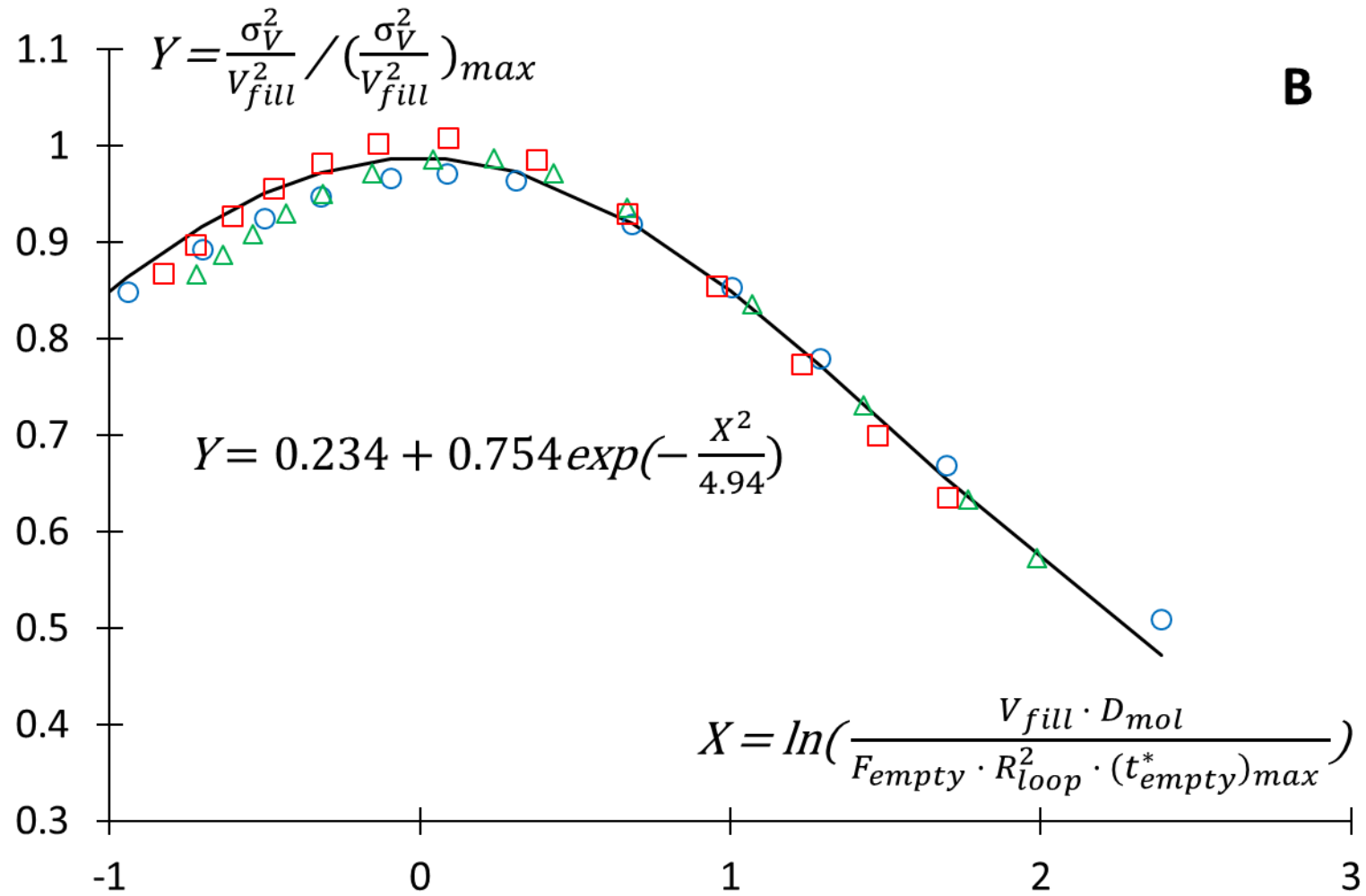
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Figure 7:

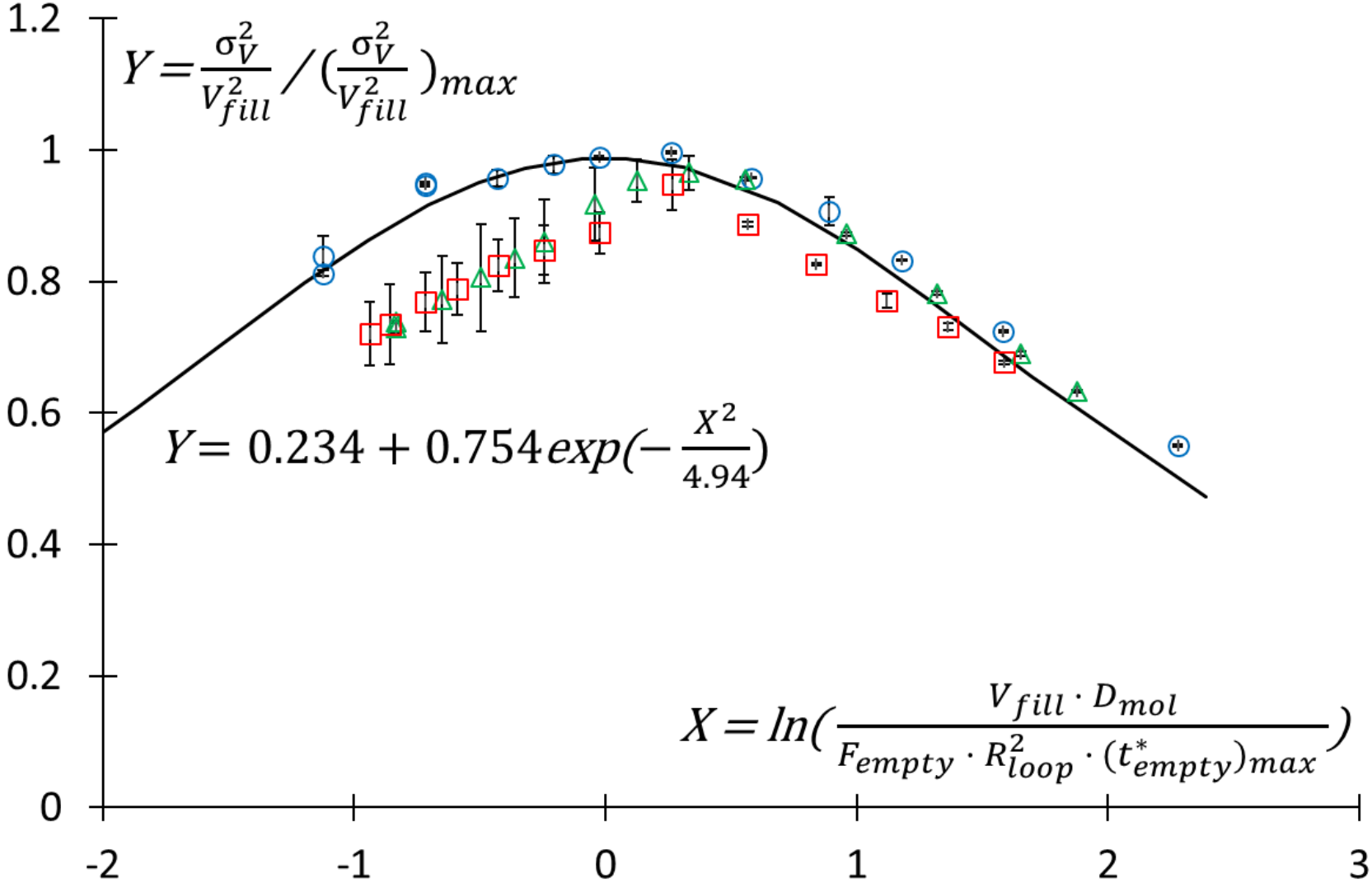
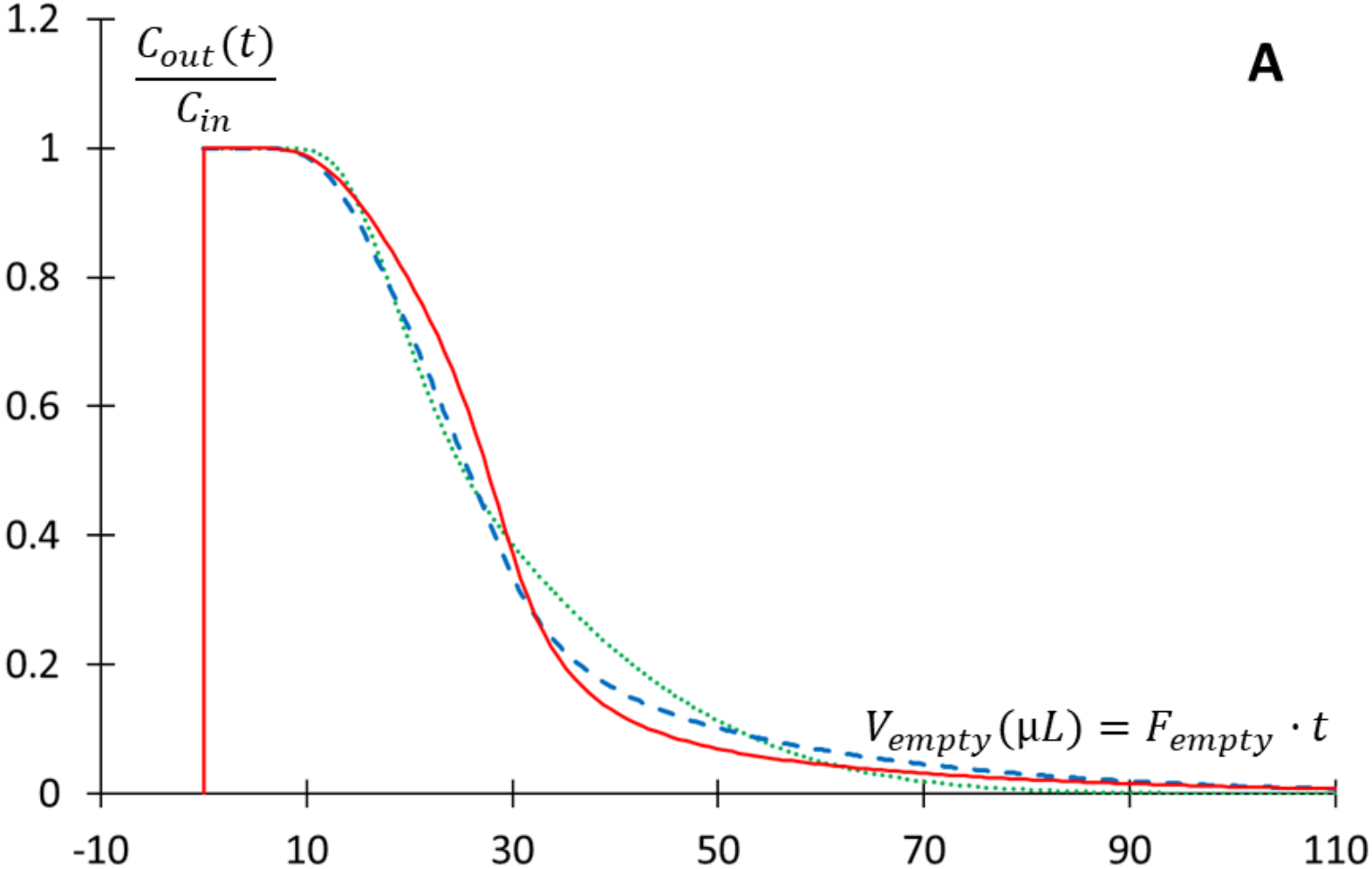


Figure 6:



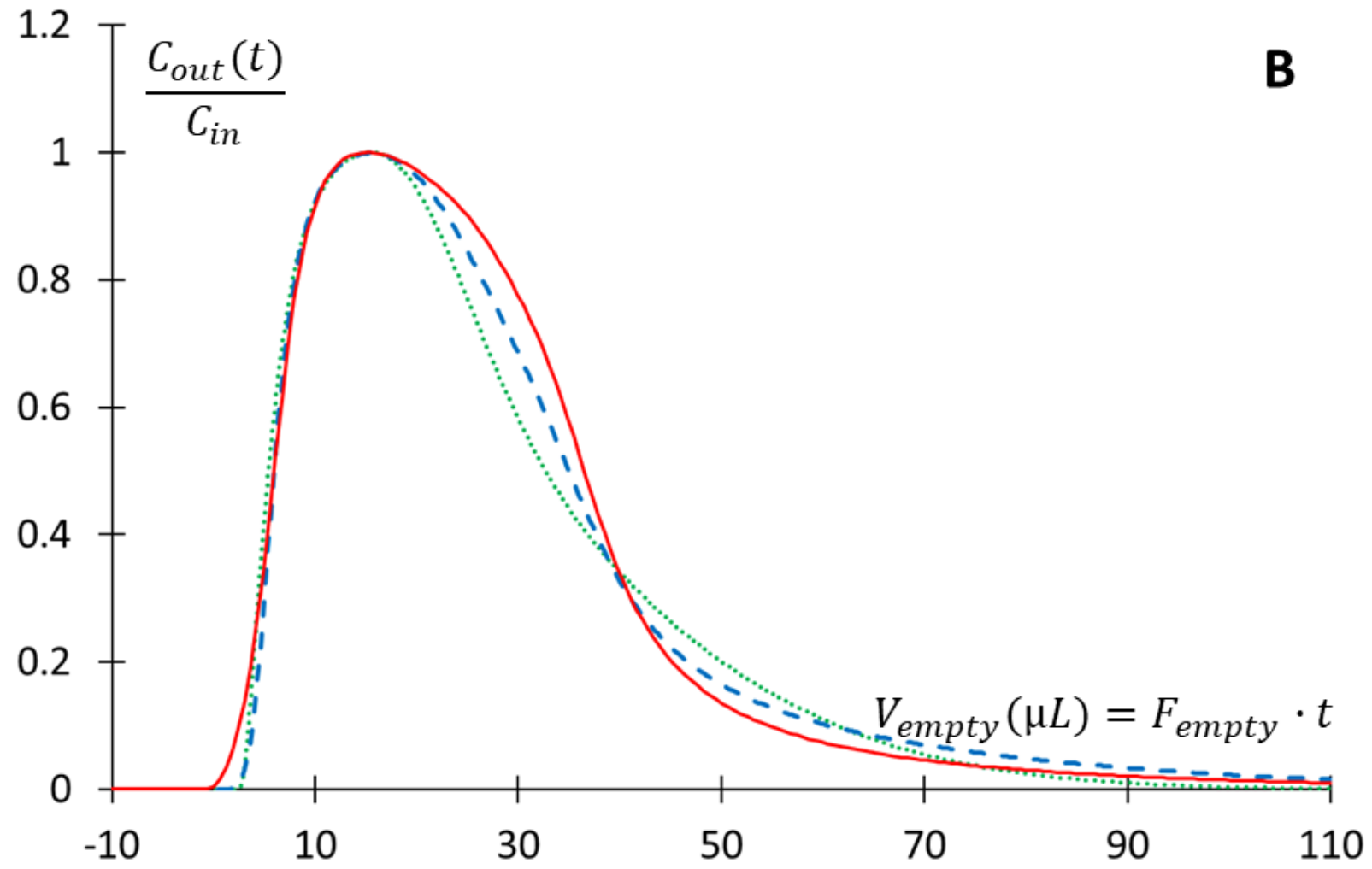
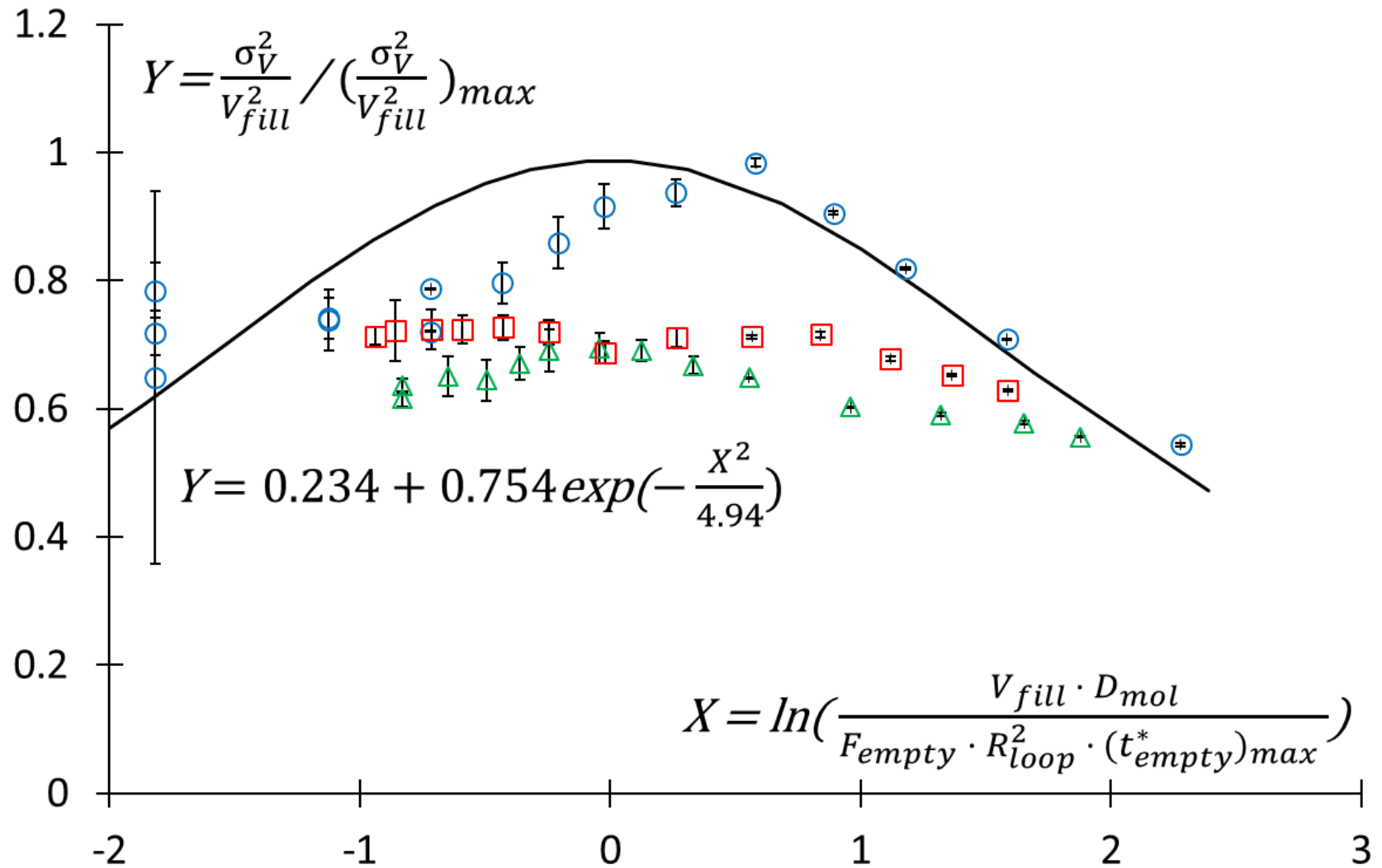
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Figure 8:



Ali Moussa: Conceptualization, Methodology, Validation, Formal analysis, Investigation (Simulations), Visualization, Writing - original draft, Data Curation.

Thomas Lauer: Validation, Investigation (Experimental), Methodology

Dwight Stoll: Conceptualization, Writing - original draft, Writing - Review & Editing, Supervision (Experimental), Funding acquisition

Gert Desmet: Conceptualization, Writing - Review & Editing, Supervision (Simulations)

Ken Broeckhoven: Conceptualization, Formal analysis, Writing - original draft, Writing - Review & Editing, Resources, Supervision (Simulations), Funding acquisition

Supplementary Material

Modelling of analyte profiles and band broadening generated by interface loops used in multi-dimensional liquid chromatography

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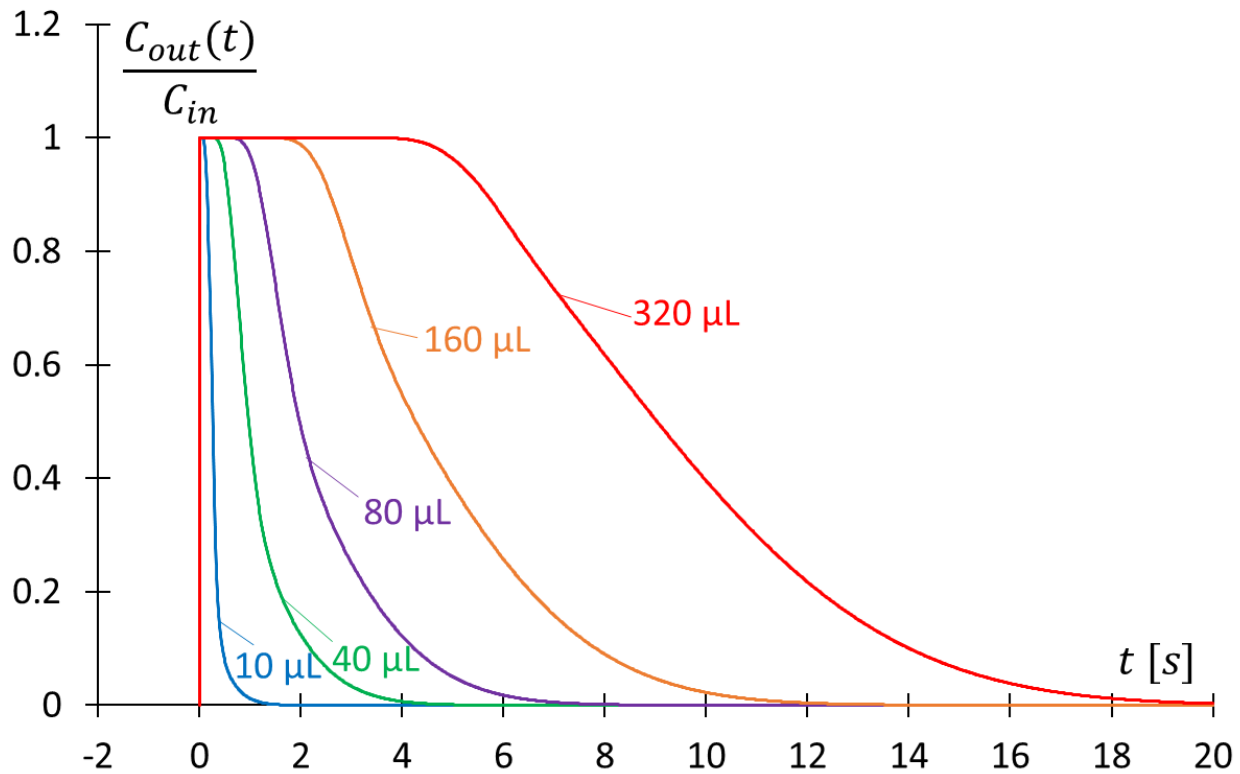
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Abstract

In section 1 (Fig. S1) of the supplementary material, an overlay of simulated elution profiles obtained for different sample volumes is shown, similar to Fig. 3A in the main article, but not dimensionless. Section 2 shows (Fig. S2) the complete simulation range of the fully normalized peak variance curve, as also shown in Fig. 5A but now including lower t_{empty}^* values not shown in the main article. In addition, the simulated absolute peak variance as a function of dimensionless elution time for different F_{empty}/F_{fill} ratios is shown in Fig. S3, in addition to the fit functions. Section 3 illustrates the simulated effect of enhanced radial dispersion that can occur as the result of centripetal forces in coiled loops at high flow rates (Fig. S4) and how this can be modelled using t_{empty}^* based on D_{rad} and t_{fill}^*/t_{empty}^* instead of F_{empty}/F_{fill} (Fig. S5). Section 4 (Fig. S6-S7) shows a comparison between the simulated and experimental normalized emptying profiles as a function of emptying volume, as also shown in Fig. 6 in the main article, but now for two other F_{empty}/F_{fill} ratios. Section 5 provides tables with all the experimental conditions (filling flow rate, emptying flow rate, actual sample volume, filling and elution times) employed in the measurements.

28 **Section 1:**



29

30

31 **Figure S1:** Simulated emptying profiles as a function of time for different sample volumes. Blue
32 $V_{fill} = 10 \mu\text{L}$, green $V_{fill} = 40 \mu\text{L}$, purple $V_{fill} = 80 \mu\text{L}$, orange $V_{fill} = 160 \mu\text{L}$, red $V_{fill} = 320 \mu\text{L}$. $F_{fill} = 0.25$
33 mL/min , $F_{empty} = 2 \text{ mL/min}$, $F_{empty}/F_{fill} = 8$, $D_{mol} = 1 \cdot 10^{-9} \text{ m}^2/\text{s}$.

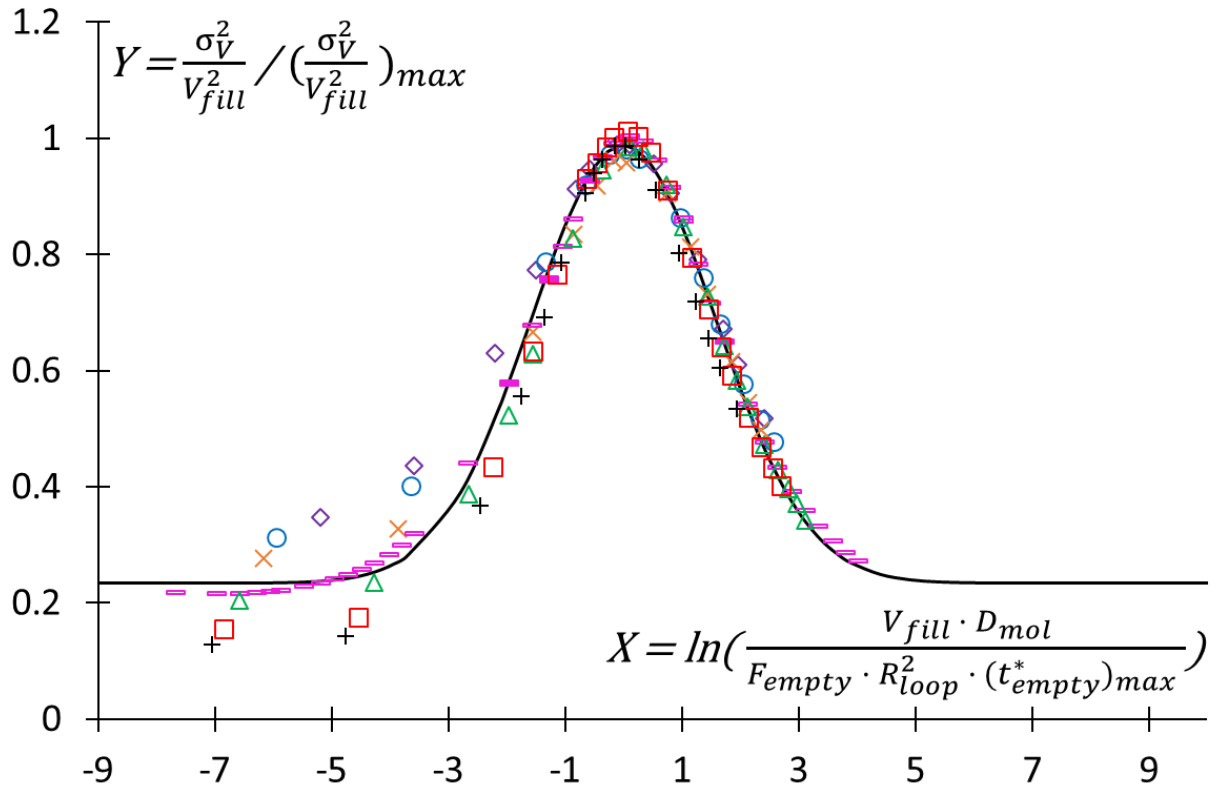
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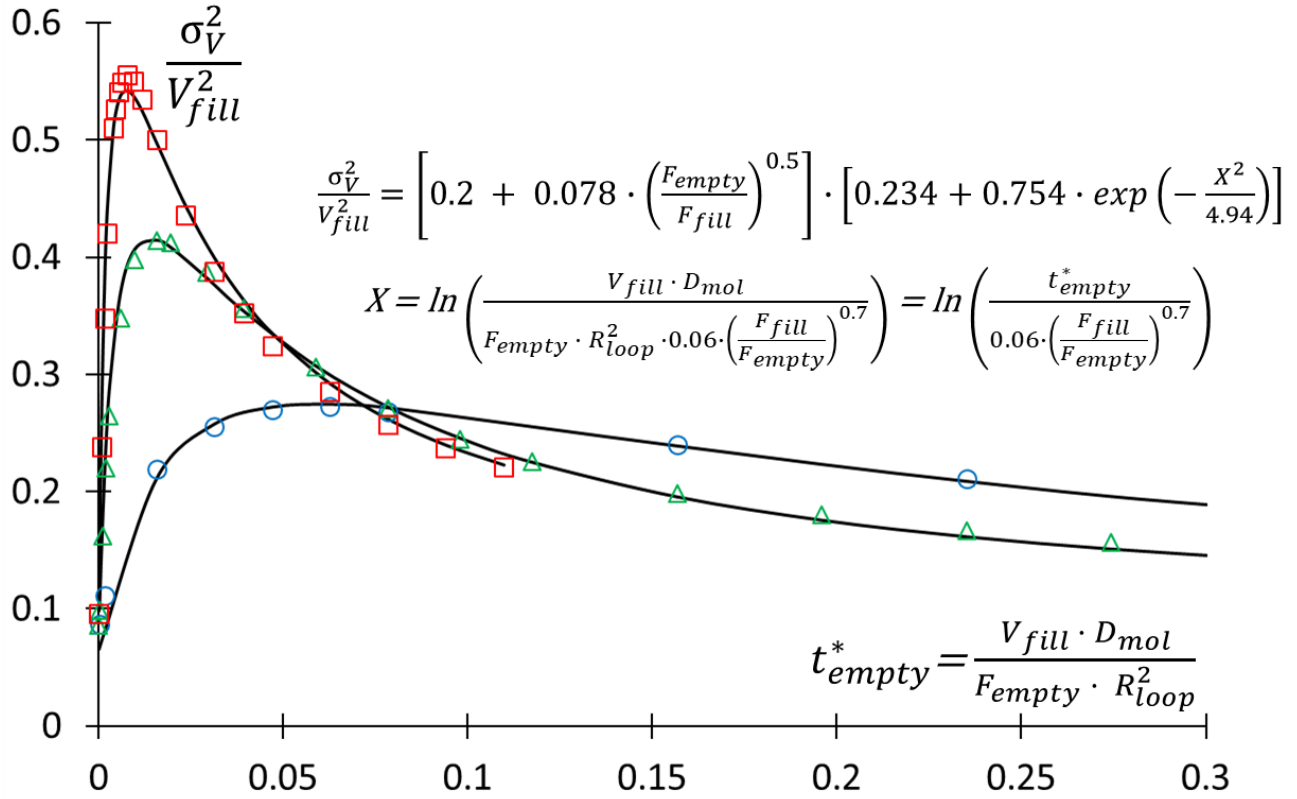
38 **Section 2:**



39
 40 **Figure S2:** The complete simulation range of the fully normalized peak variance curve (black solid
 41 curve representing the fit Eq. (10)) in addition to the simulated data points of the different
 42 F_{empty}/F_{fill} ratios. $F_{empty}/F_{fill} = 0.7$ (purple diamonds), 1 (blue circles), 2 (orange crosses), 7 (pink
 43 hyphens), 8 (green triangles), 20 (red squares), 40 (black pluses).

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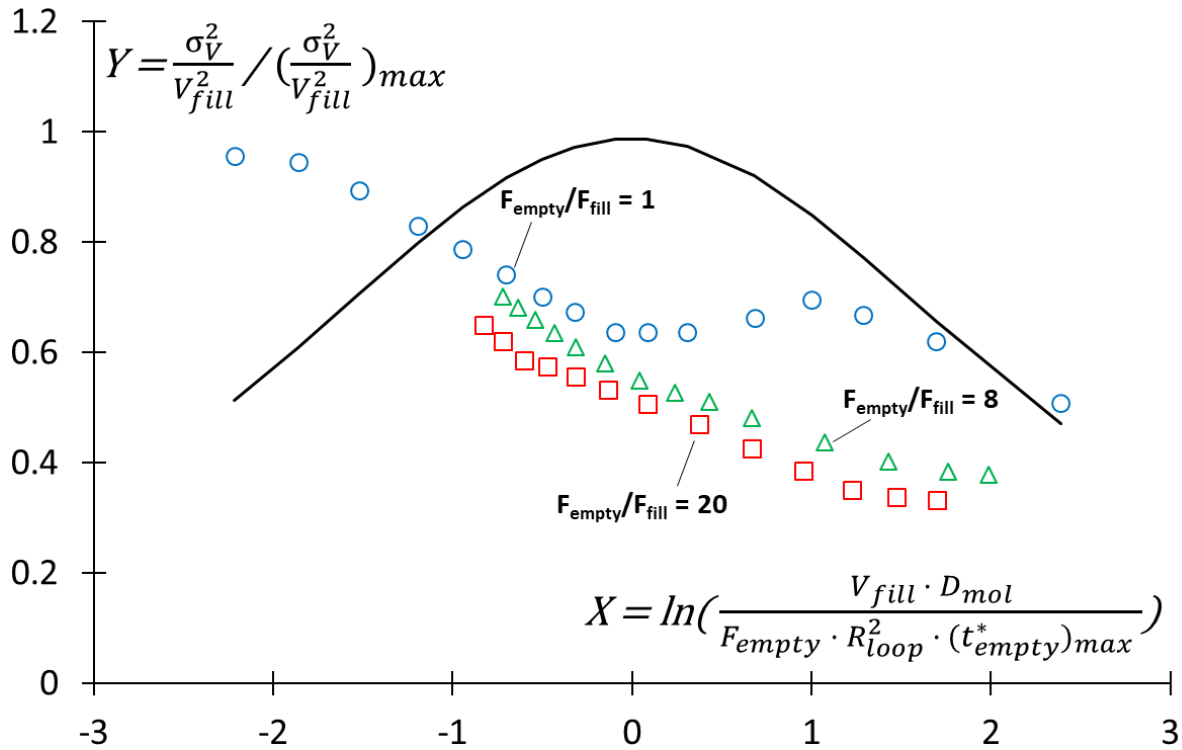
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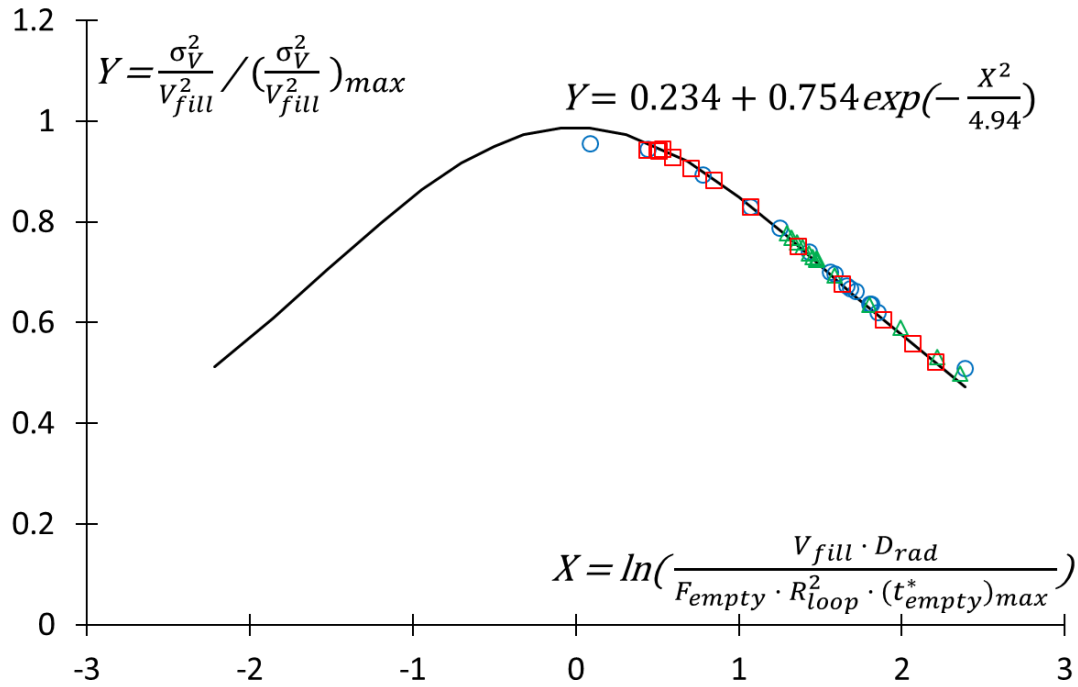
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 47 **Figure S3:** Simulated absolute peak variance as a function of dimensionless emptying time for
 48 different F_{empty}/F_{fill} ratios: $F_{empty}/F_{fill} = 1$ (blue circles), $F_{empty}/F_{fill} = 8$ (green triangles) and $F_{empty}/F_{fill} =$
 49 20 (red squares). The black lines represent the fit equation in the emptying time domain.

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52 **Section 3:**



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 54 **Figure S4:** Fully normalized peak variance curve (black solid curve representing the fit equation) in
 55 addition to the simulated data points of the F_{empty}/F_{fill} ratios obtained with a fixed loop filling
 56 volume of $V_{fill} = 30 \mu\text{L}$. An enhanced radial dispersion coefficient D_{rad} ($D_{rad} = D_{mol} \times \text{factor}$
 57 representing the increase in radial dispersion) was used instead of D_{mol} in the simulations. F_{empty}/F_{fill}
 58 = 1 and $D_{mol} = 5.56 \cdot 10^{-10} \text{ m}^2/\text{s}$ (blue circles), $F_{empty}/F_{fill} = 8$ and $D_{mol} = 5.56 \cdot 10^{-10} \text{ m}^2/\text{s}$ (green triangles),
 59 $F_{empty}/F_{fill} = 20$ and $D_{mol} = 2.74 \cdot 10^{-10} \text{ m}^2/\text{s}$ (red squares).



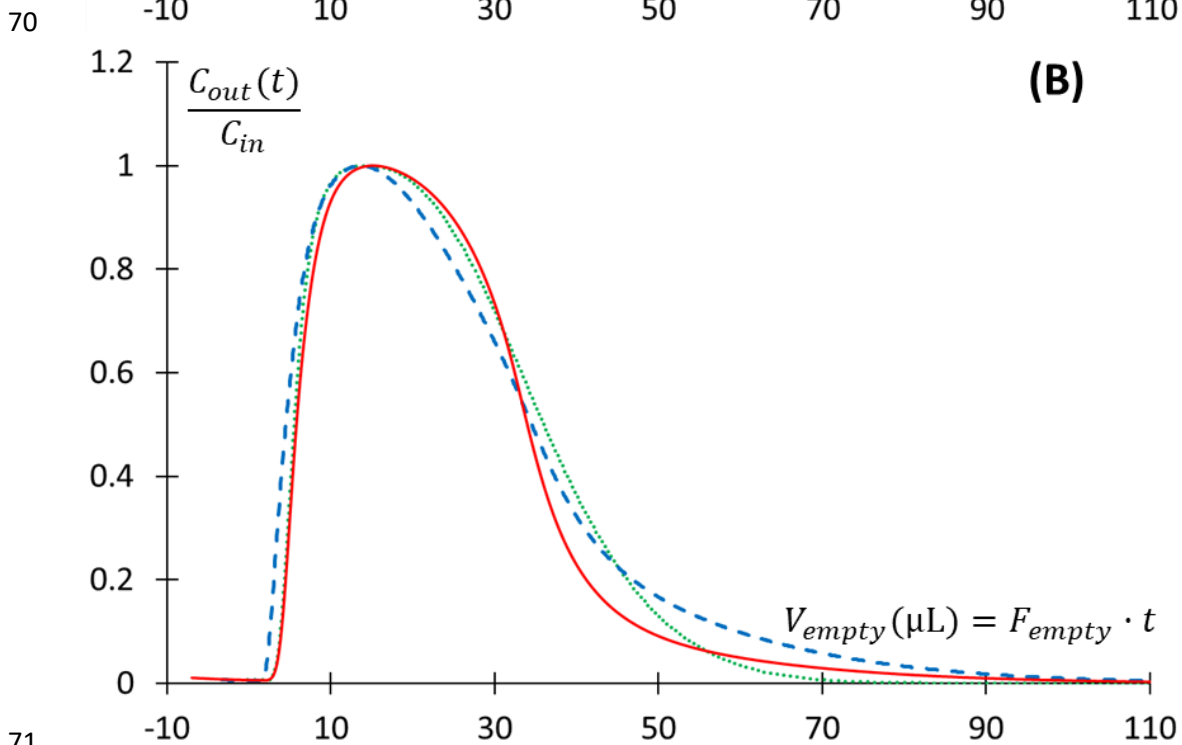
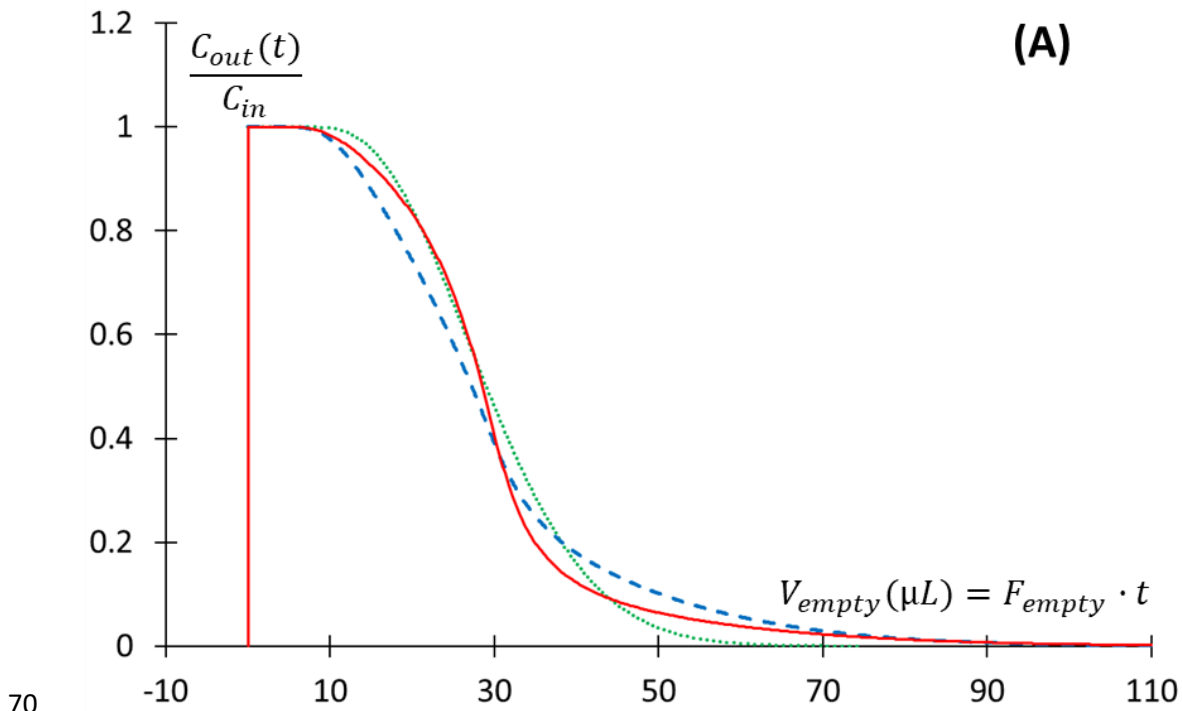
60

61 **Figure S5:** Fully normalized peak variance curve (black solid curve representing the fit equation) in addition
 62 to the simulated data points of the different F_{empty}/F_{fill} ratios obtained with a fixed loop filling volume of V_{fill}
 63 = 30 μ L. An enhanced radial dispersion coefficient D_{rad} ($D_{rad} = D_{mol} \times$ factor representing increase in radial
 64 dispersion) was used instead of D_{mol} in the simulations. D_{rad} and t_{fill}^*/t_{empty}^* were used in the fit equation
 65 and x-axis instead of D_{mol} and F_{empty}/F_{fill} . **Blue circles:** $F_{empty}/F_{fill} = 1$ and $D_{mol} = 5.56 \cdot 10^{-10}$ m²/s, **green triangles:**
 66 $F_{empty}/F_{fill} = 8$ and $D_{mol} = 5.56 \cdot 10^{-10}$ m²/s, **red squares:** $F_{empty}/F_{fill} = 20$ and $D_{mol} = 2.74 \cdot 10^{-10}$ m²/s.

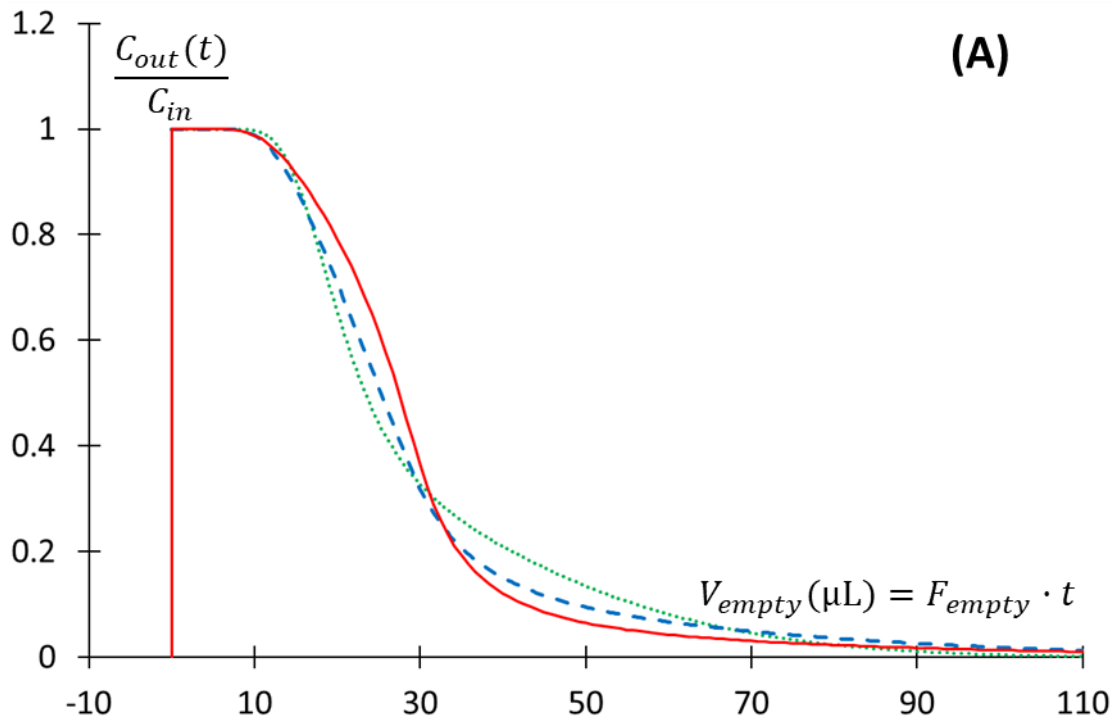
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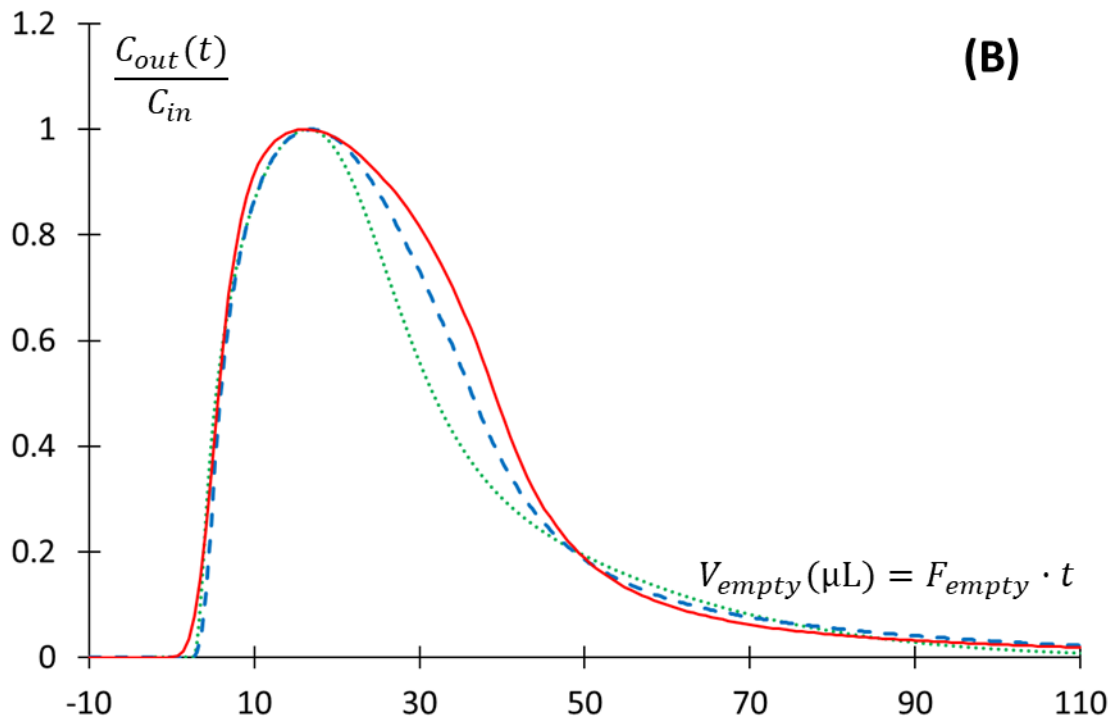
69 **Section 4:**



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 72 **Figure S6:** Normalized emptying profiles as a function of emptying volume (A) simulated and (B)
 73 experimental. For both $F_{empty}/F_{fill} = 1$ and $D_{mol} = 5.56 \cdot 10^{-10} \text{ m}^2/\text{s}$. **Green dotted curves:** $F_{fill} = F_{empty} =$
 74 0.05 ml/min , $t_{empty,sim}^* = 0.654$, $t_{empty,exp}^* = 0.585$. **Blue dashed curves:** $F_{fill} = F_{empty} = 0.50 \text{ mL/min}$,
 75 $t_{empty,sim}^* = 0.065$, $t_{empty,exp}^* = 0.058$. **Red solid curves:** $F_{fill} = F_{empty} = 1.4 \text{ mL/min}$, $t_{empty,sim}^* = 0.023$,
 76 $t_{empty,exp}^* = 0.019$.



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80 **Figure S7:** Normalized emptying profiles as a function of emptying volume (A) simulated and (B)
 81 experimental. For both $F_{empty}/F_{fill} = 20$ and $D_{mol} = 2.74 \cdot 10^{-10} \text{ m}^2/\text{s}$. **Green dotted curves:** $F_{fill} = 0.02$
 82 ml/min , $F_{empty} = 0.4 \text{ ml}/\text{min}$, $t^*_{empty,sim} = 0.040$, $t^*_{empty,exp} = 0.036$. **Blue dashed curves:** $F_{fill} = 0.1 \text{ ml}/\text{min}$, F_{empty}
 83 $= 2 \text{ ml}/\text{min}$, $t^*_{empty,sim} = 0.008$, $t^*_{empty,exp} = 0.007$. **Red solid curves:** $F_{fill} = 0.25 \text{ ml}/\text{min}$, $F_{empty} = 5 \text{ ml}/\text{min}$,
 84 $t^*_{empty,sim} = 0.003$, $t^*_{empty,exp} = 0.003$.

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86 **Section 5:**

87 **Table TS1:**

- 88 ● Mobile phase: 50/50 MeOH/H₂O, $D_{mol} = 5.56 \cdot 10^{-10} \text{ m}^2/\text{s}$
- 89 ● Flow rate ratio (F_{elu}/F_{fill}) = 8
- 90 ● Capillary = 780 mm x 370 μm I.D.
- 91 ● Loop Flush Volume = 800% V_{inj} to ensure C falls below $C_{max} / 1000$
- 92 ● 5 repeats for each row.
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#	F_{fill} (mL/min)	F_{empty} (mL/min)	Filling time (min)	Emptying time (min)*	V_{inj} (μL)
1	0.04	0.32	0.750	0.750	30
2	0.05	0.40	0.600	0.600	30
3	0.07	0.56	0.429	0.429	30.03
4	0.10	0.8	0.300	0.300	30
5	0.15	1.2	0.200	0.200	30
6	0.19	1.52	0.158	0.158	30.02
7	0.23	1.84	0.130	0.130	29.9
8	0.28	2.24	0.107	0.107	29.96
9	0.34	2.72	0.088	0.088	29.92
10	0.40	3.2	0.075	0.075	30
11	0.45	3.6	0.067	0.067	30.15
12	0.50	4	0.060	0.060	30
13	0.55	4.4	0.055	0.055	30.25
14	0.60	4.8	0.050	0.050	30

94 * Emptying time $t_{empty} = V_{fill}/F_{empty}$

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Table TS2:

- Mobile phase: 50/50 MeOH/H₂O, $D_{mol} = 5.56 \cdot 10^{-10} \text{ m}^2/\text{s}$
- Flow rate ratio (F_{elu}/F_{fill}) = 1
- Capillary = 780 mm x 370 μm I.D.
- Loop Flush Volume = 800% V_{inj} to ensure C falls below $C_{max} / 1000$
- 5 repeats for each row.

#	F_{fill} (mL/min)	F_{empty} (mL/min)	Filling Time (min)	Emptying Time (min)	V_{inj} (μL)
1	0.05	0.05	0.600	4.800	30
2	0.1	0.1	0.300	2.400	30
3	0.15	0.15	0.200	1.600	30
4	0.2	0.2	0.150	1.200	30
5	0.275	0.275	0.109	0.873	29.975
6	0.4	0.4	0.075	0.600	30
7	0.5	0.5	0.060	0.480	30
8	0.6	0.6	0.050	0.400	30
9	0.75	0.75	0.040	0.320	30
10	0.9	0.9	0.033	0.267	29.7
11	1.1	1.1	0.027	0.218	29.7
12	1.4	1.4	0.021	0.171	29.4
13	1.8	1.8	0.017	0.133	30.6
14	2.5	2.5	0.012	0.096	30
15	3.5	3.5	0.009	0.069	31.5
16	5	5	0.006	0.048	30

101 **Table TS3:**

- 102 ● Mobile phase: 50/50 IPA/H₂O, $D_{mol} = 2.74 \cdot 10^{-10} \text{ m}^2/\text{s}$
- 103 ● Flow rate ratio (F_{elu}/F_{fill}) = 20
- 104 ● Capillary = 780 mm x 370 μm I.D.
- 105 ● Loop Flush Volume = 800% V_{inj} to ensure C falls below $C_{max} / 1000$
- 106 ● 5 repeats for each row.

#	F _{fill} (mL/min)	F _{empty} (mL/min)	Filling Time (min)	Emptying Time (min)	V _{inj} (μL)
1	0.020	0.400	1.500	0.600	30
2	0.025	0.500	1.200	0.480	30
3	0.032	0.640	0.938	0.375	30.016
4	0.042	0.840	0.714	0.286	29.988
5	0.056	1.120	0.536	0.214	30.016
6	0.075	1.500	0.400	0.160	30
7	0.100	2.000	0.300	0.120	30
8	0.125	2.500	0.240	0.096	30
9	0.150	3.000	0.200	0.080	30
10	0.175	3.500	0.171	0.069	29.925
11	0.200	4.000	0.150	0.060	30
12	0.225	4.500	0.133	0.053	29.925
13	0.250	5.000	0.120	0.048	30

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